## Advanced concepts of DFT: higher dimensions

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## Dynamic fields of varying dimensionality

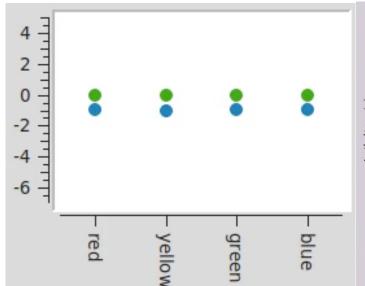
- O-dimensional: nodes, "on" vs "off" states
- I, 2, 3, 4... dimensions: peak/ blob states

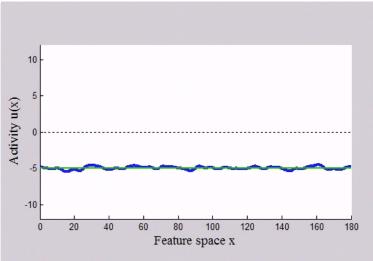
3-dimensional

2-dimensional



I-dimensional

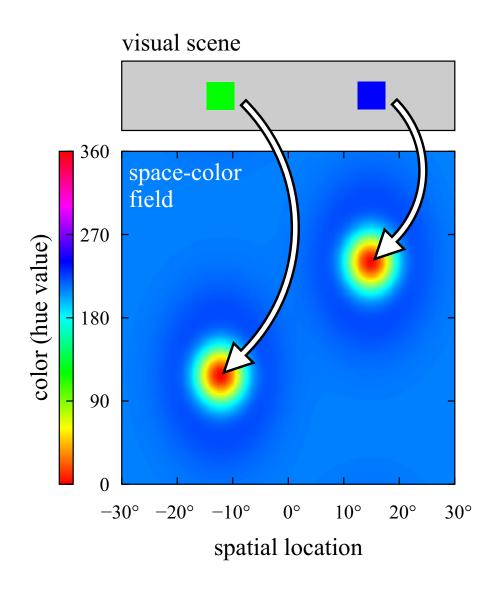




# New cognitive functions emerge as dimensionality is varied

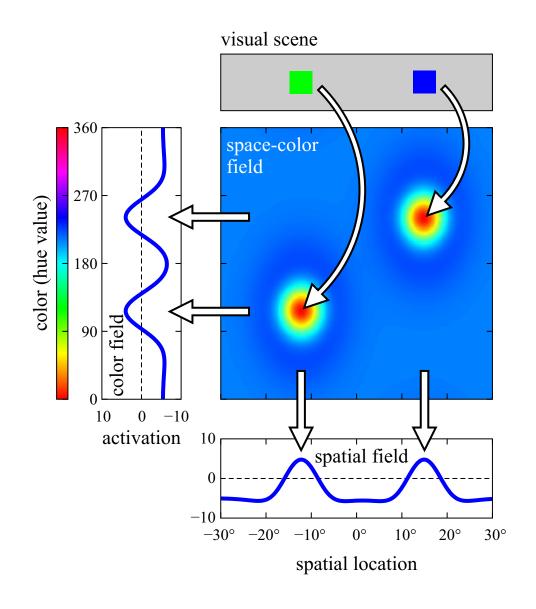
#### Binding

a joint representation of space and color



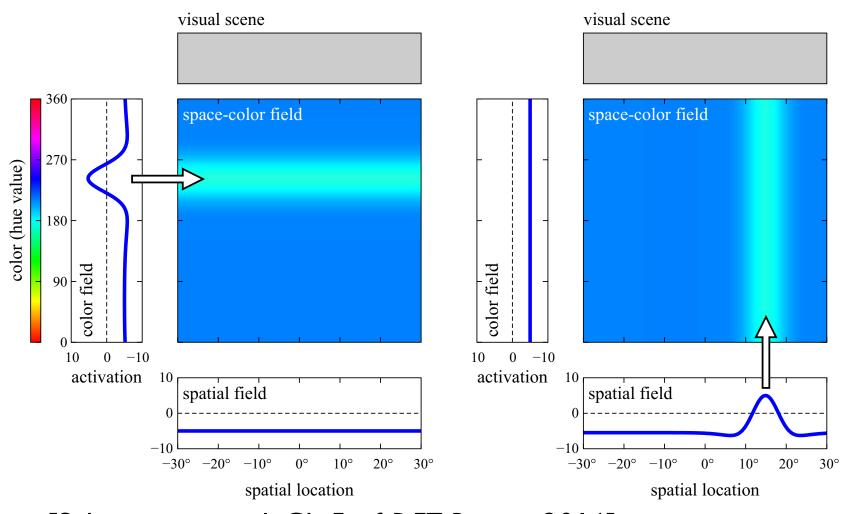
#### Extract bound features

- by projecting to lowerdimensional fields
- summing along the marginalized dimensions
- (or by taking the softmax)



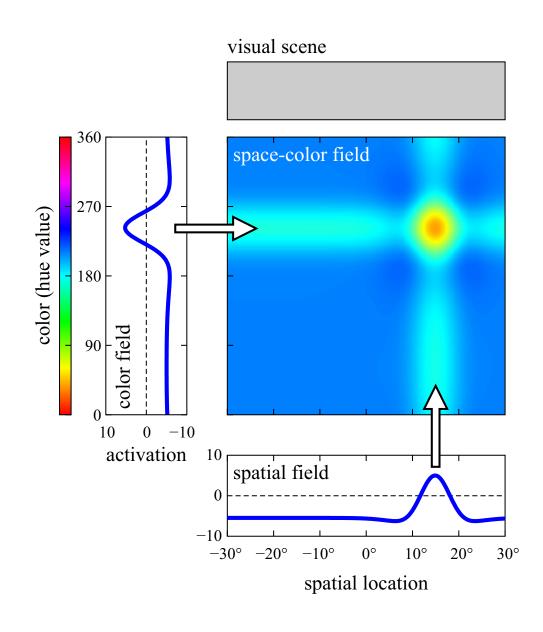
#### Assembling bound representations

projecting into higher-dimensional field by "ridge input"



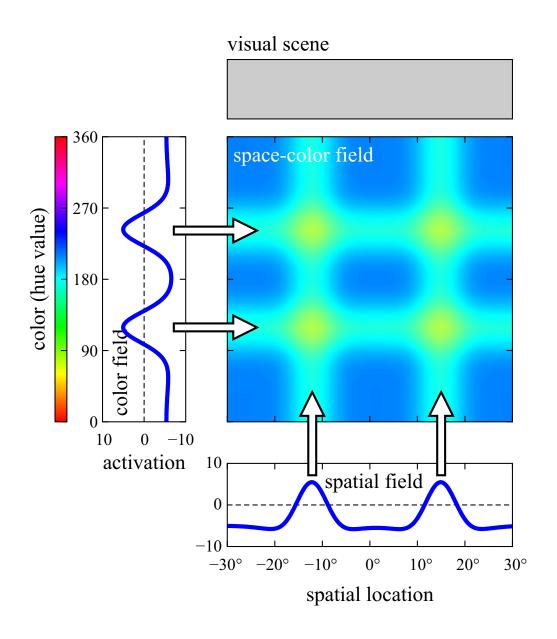
[Schneegans et al., Ch 5 of DFT Primer, 2016]

#### Assembling bound representations



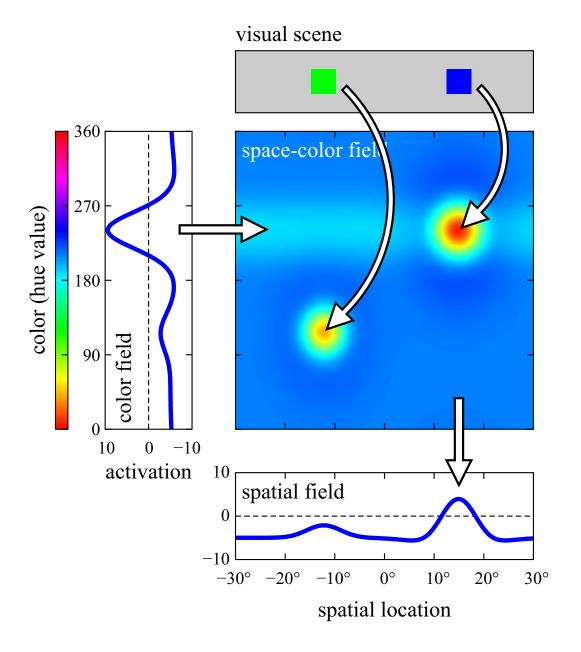
#### Assembling bound representations

- binding problem: multiple ridges lead to a correspondence problem
- => assemble one object at a time... sequentiality bottleneck!



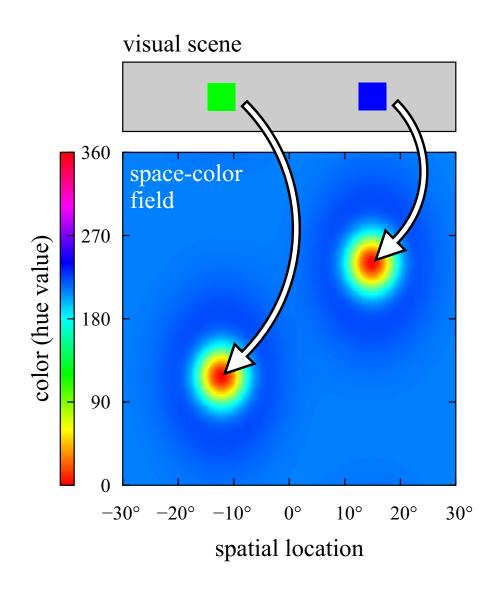
#### Visual search

=> Raul Grieben's case study



#### Binding by joint representations

- a "neuro-anatomical" form of binding
- => very costly

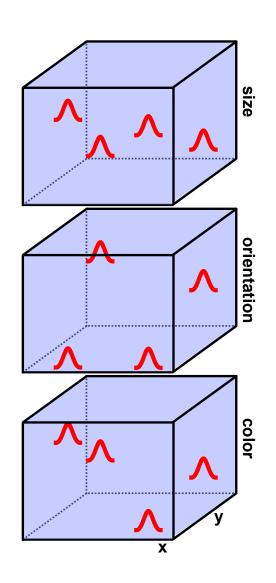


#### Binding by joint representations

- example: bind orientation, color, texture, scale, and 2D visual space => 6-dimensional field
- 100 neurons per dimension => 10<sup>12</sup> neurons ~ the entire brain!

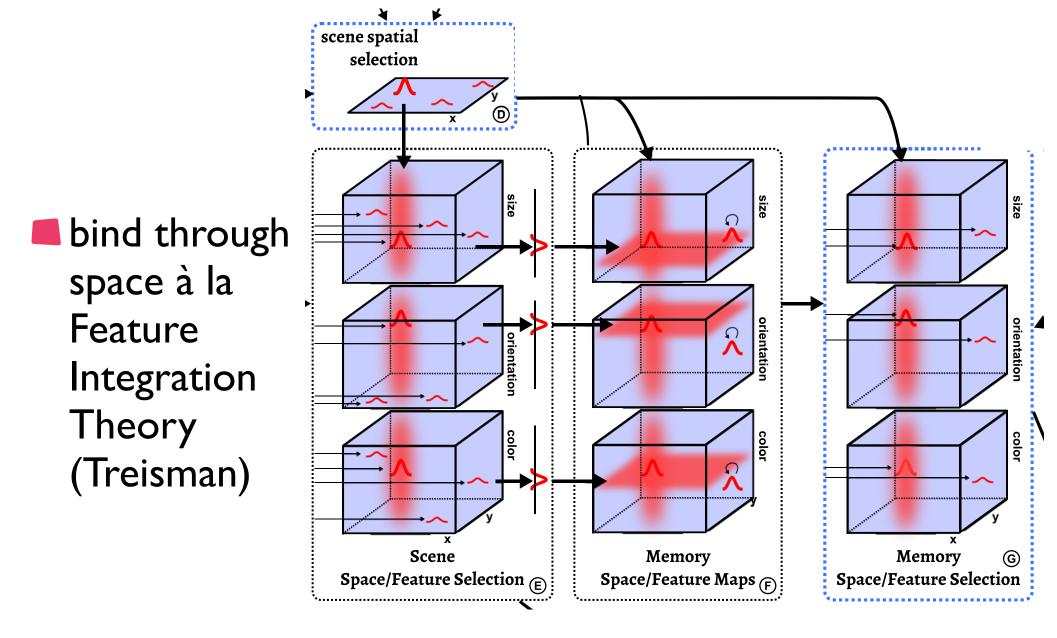
#### Binding through space

- separate 3 to 4 dimensional feature fields
- all of which share the dimension visual space (~all neurons have receptive fields)
- bind through space à la Feature Integration Theory (Treisman)

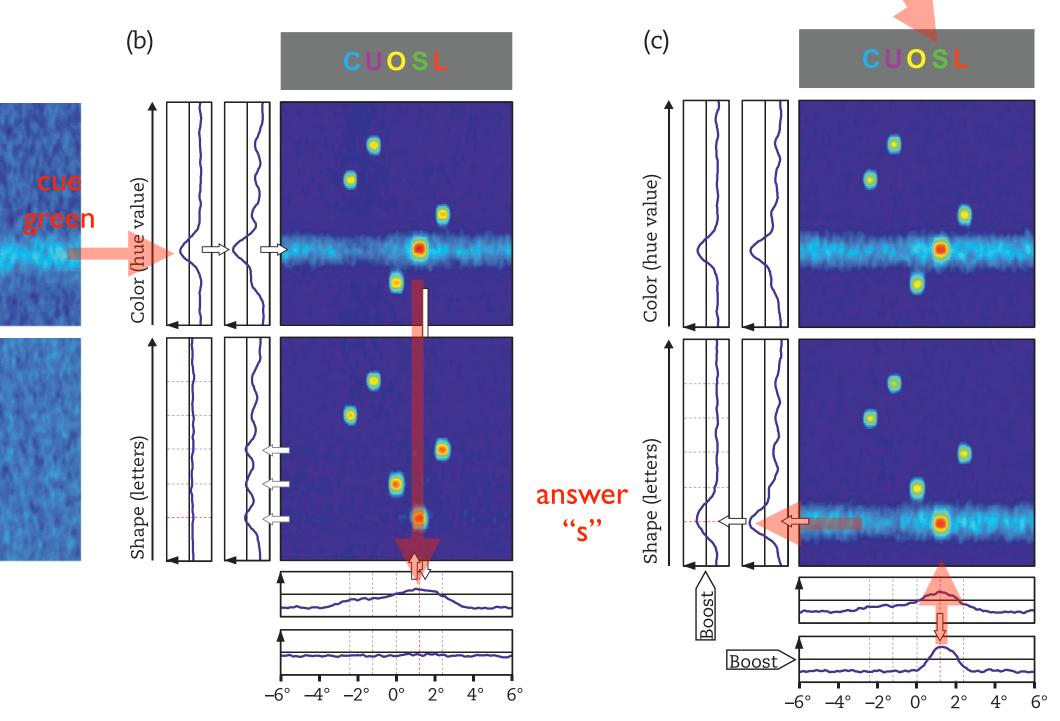


[Grieben et al. Attention, Perception & Psychophysics 2020]

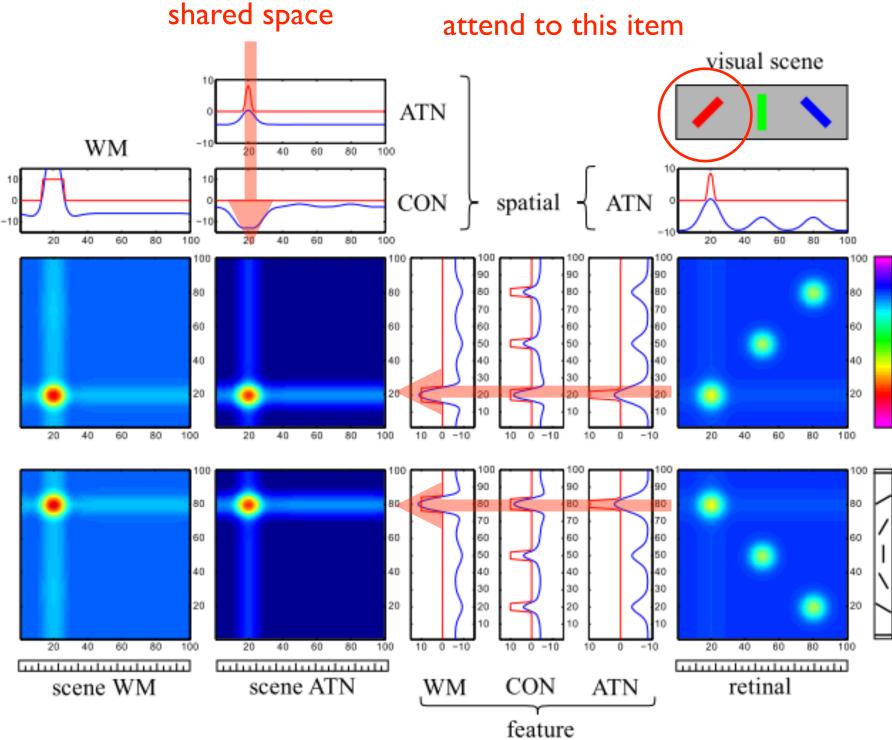
#### Binding through space



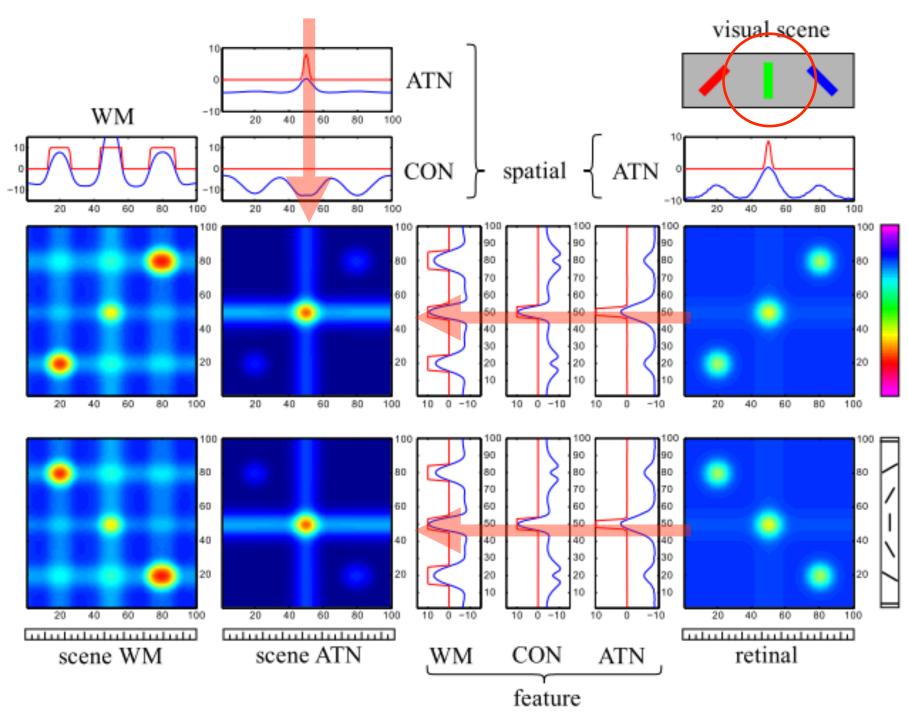
[Grieben et al. Attention, Perception & Psychophysics 2020]



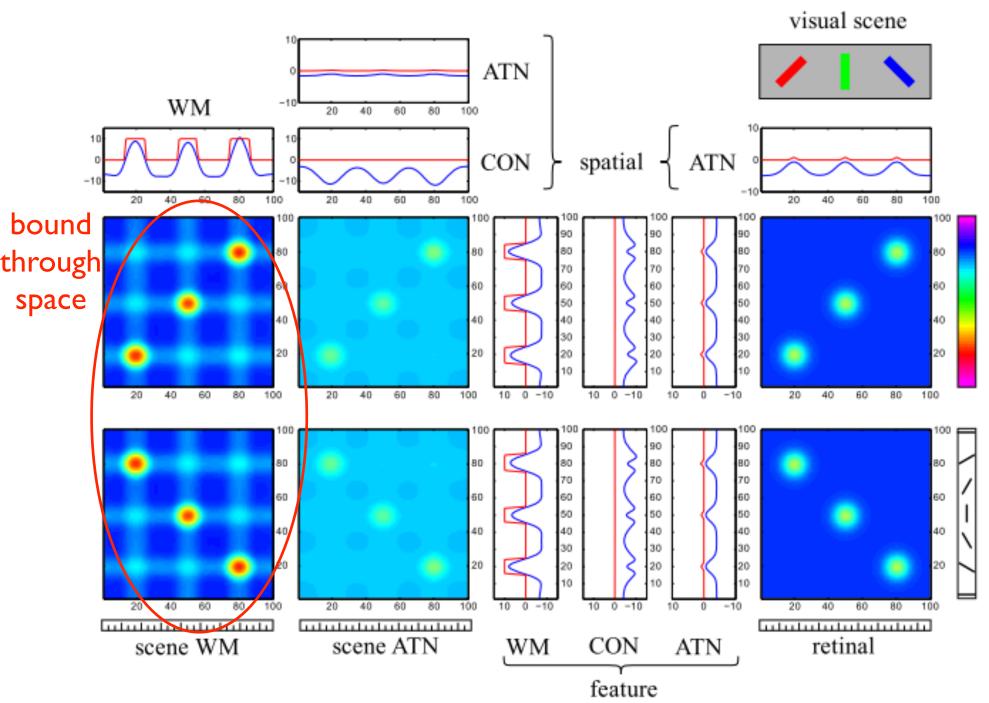
[Schneegans et al., Ch 5 of DFT Primer, 2016]



[Schneegans et al., Ch 8 of DFT Primer, 2016]



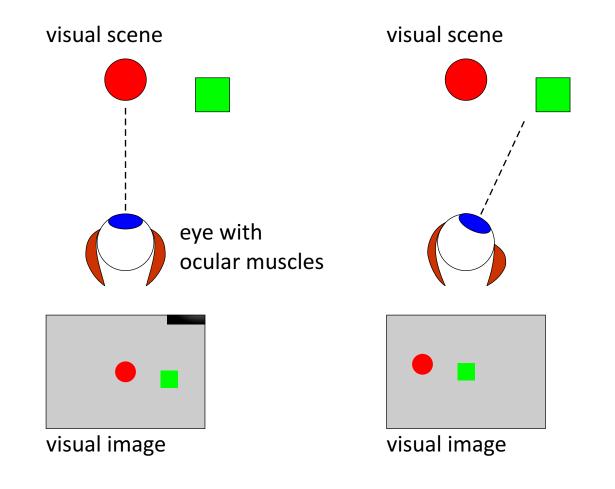
[Schneegans et al., Ch 5 of DFT Primer, 2016]



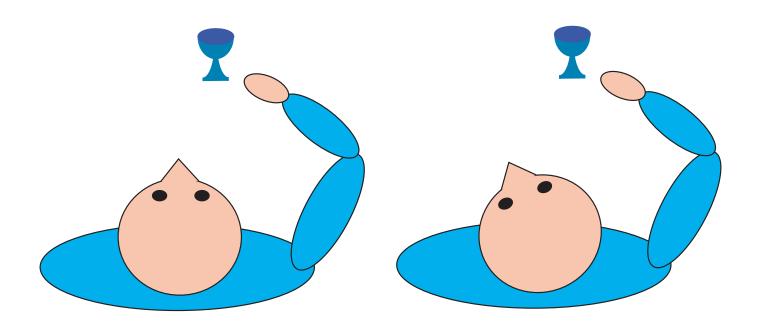
[Schneegans et al., Ch 5 of DFT Primer, 2016]

Indamental element of sensori-motor, but also of mental operations!

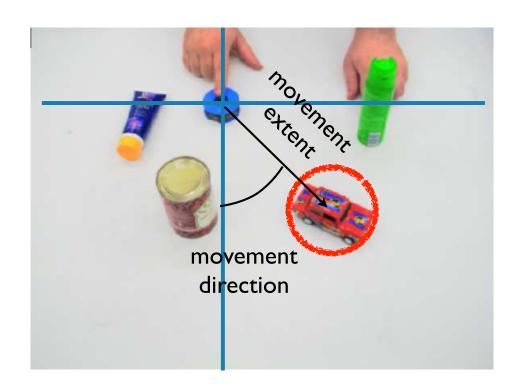
eye movement: from retinal to body-centered representation (e.g. for reaching)



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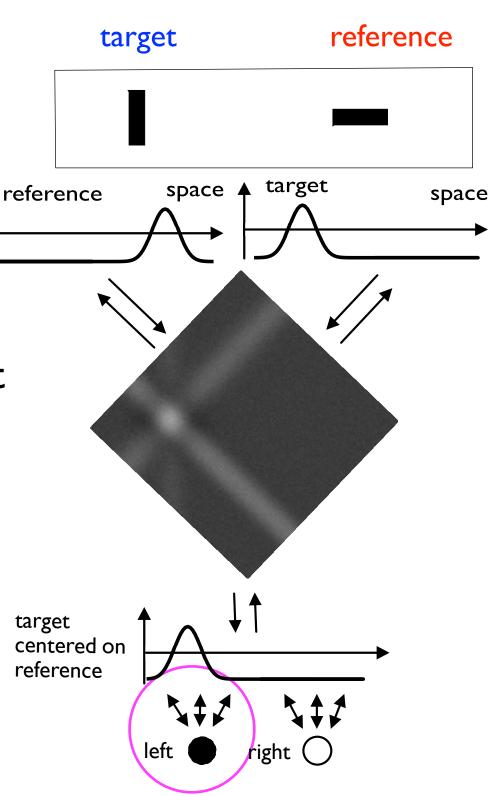
hand movement: from body-centered to hand-centered representation



relational concepts: from visual space to frame centered in reference object

e.g. "vertical object to the left of horizontal object"

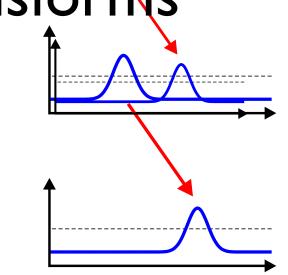
=> Mathis Richter's tutorial

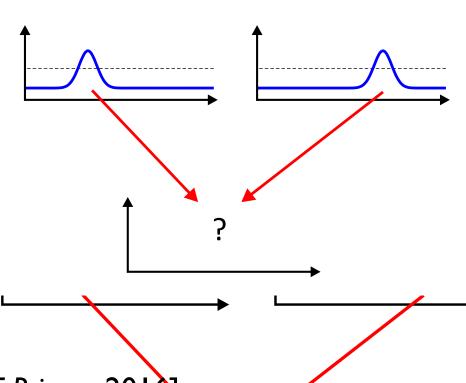


fixed mapping: neural projection in a neural network

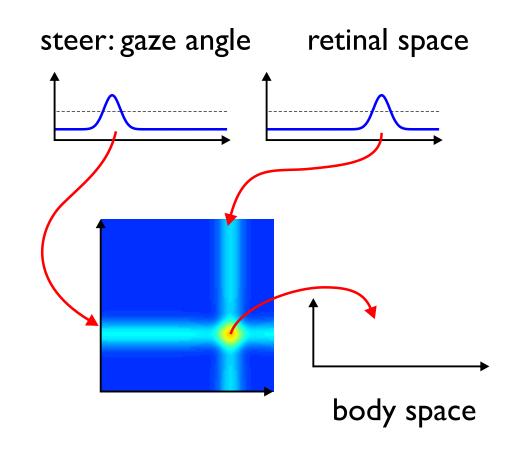


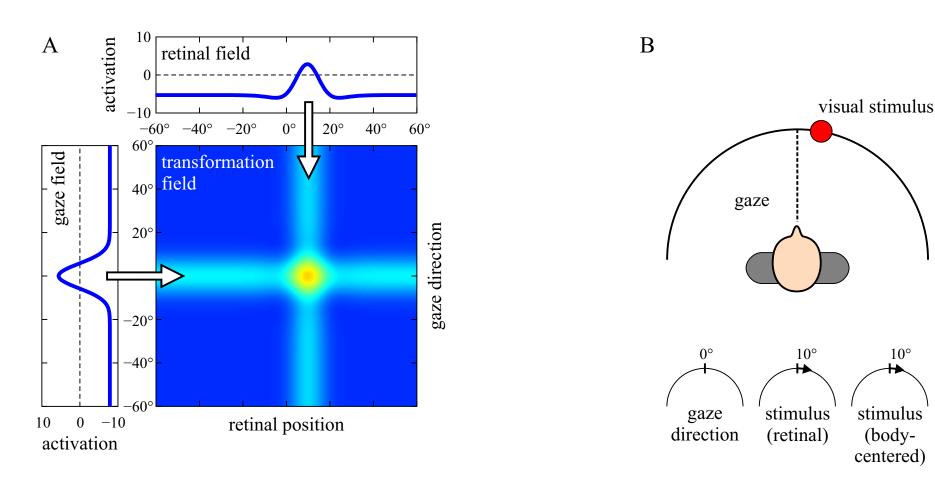
- x=gaze direction
- x=hand position
- x=position of reference object

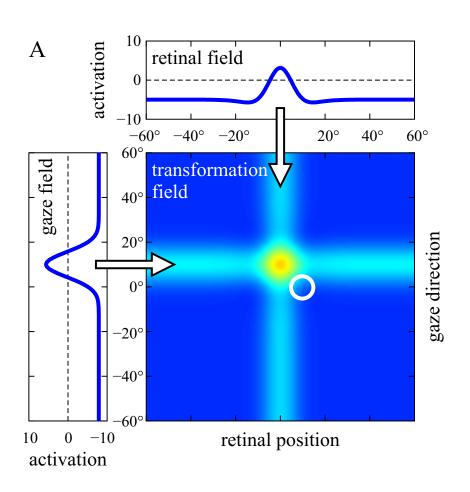


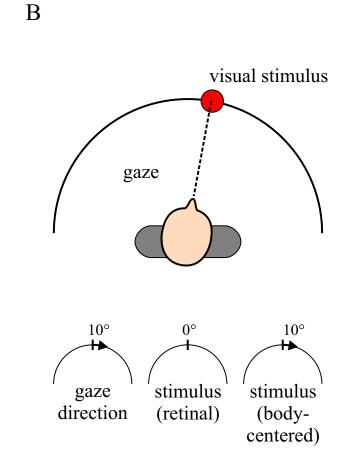


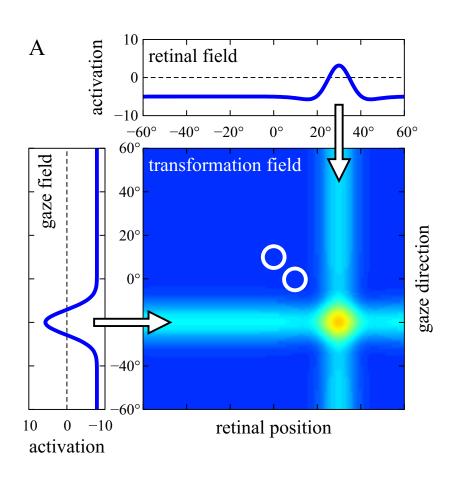
- a joint representation of
  - the space to be mapped
  - the steering space
- bind the two spaces
- project out to transformed space

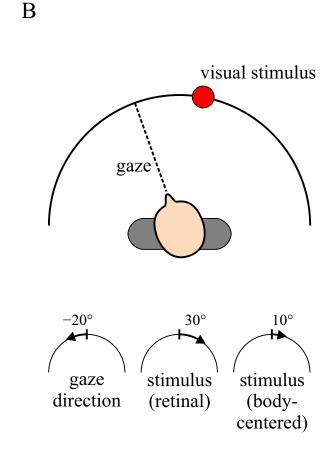


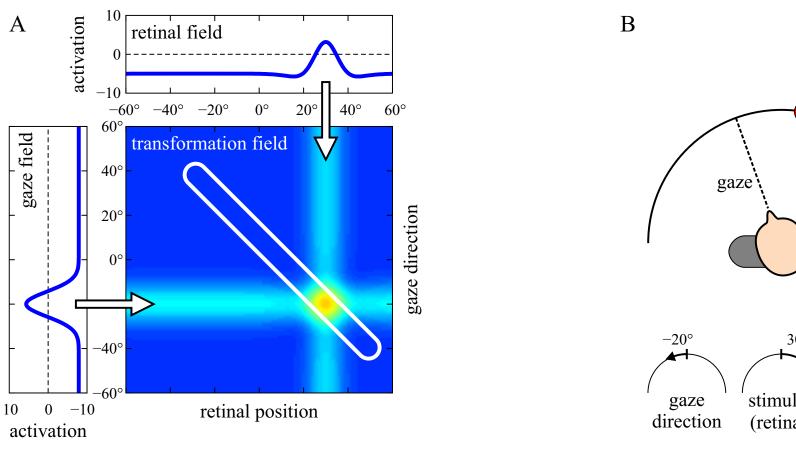


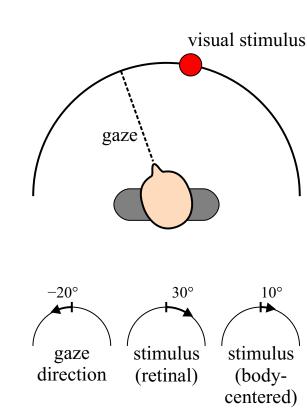


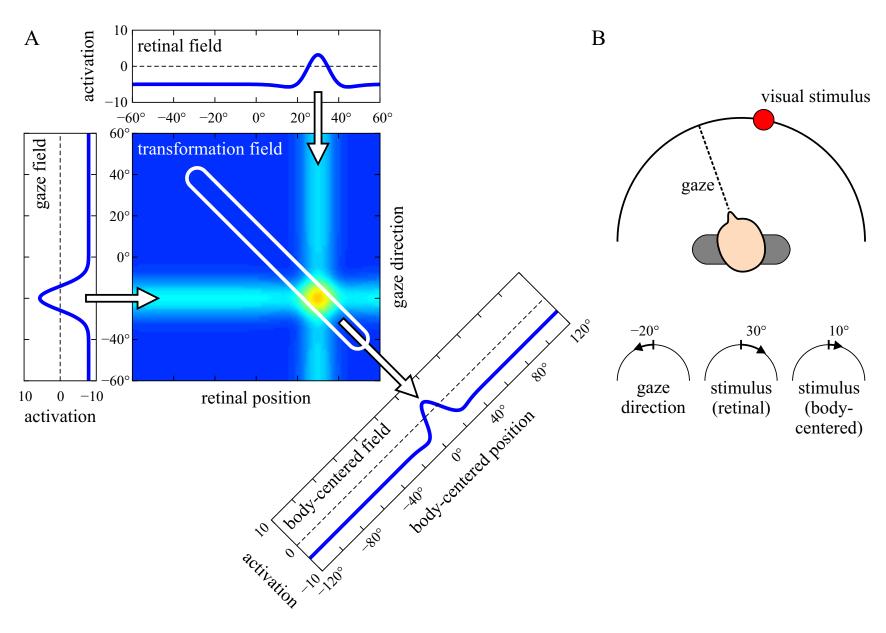




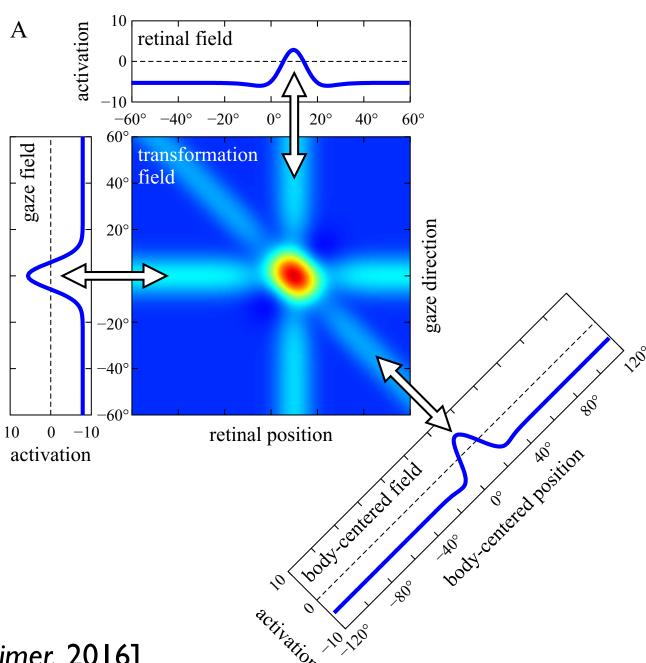




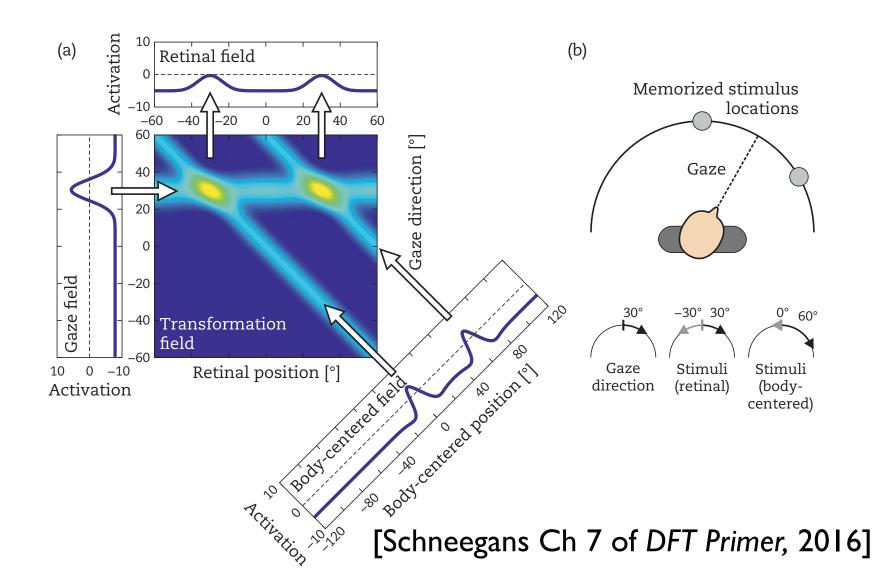




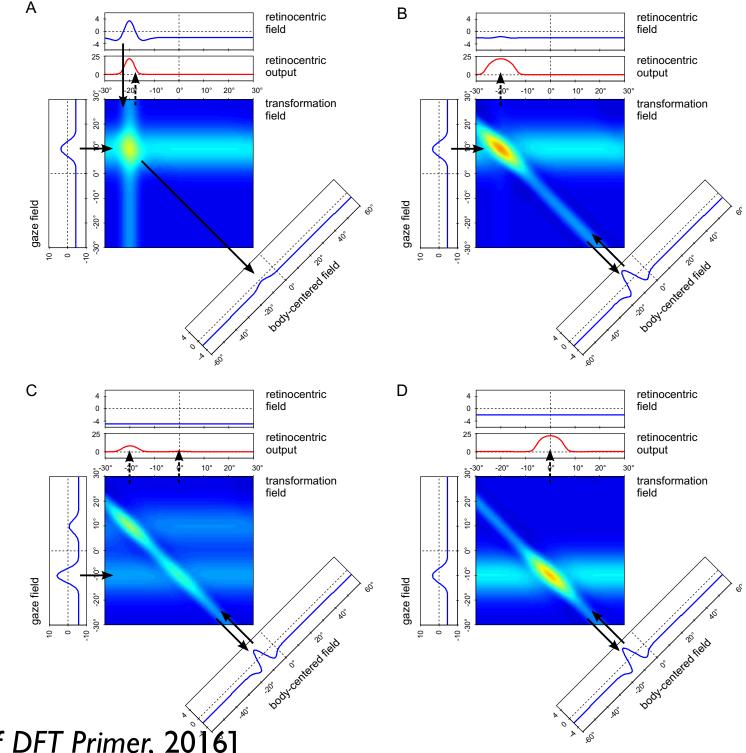
- bi-directional coupling
- enables new functions



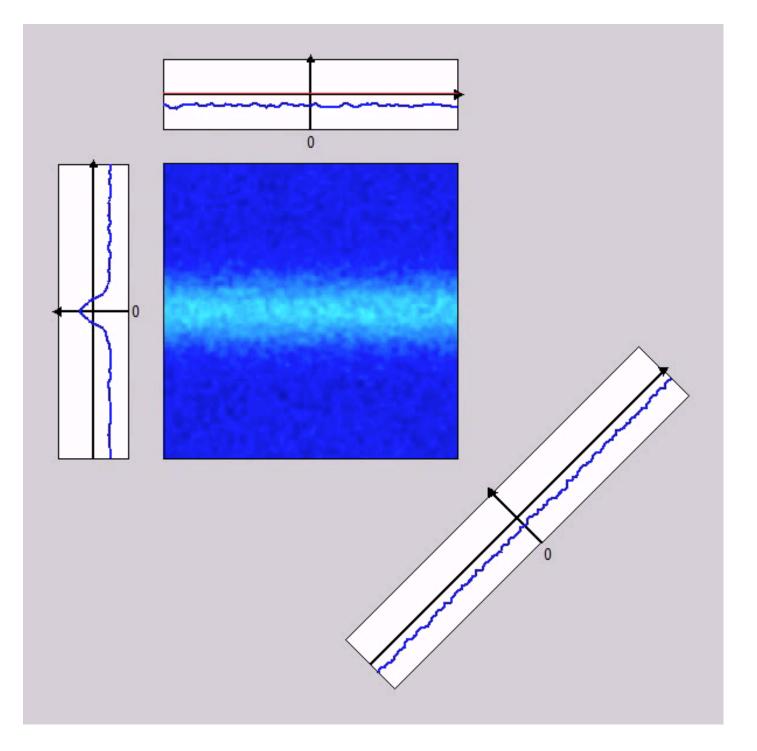
predict retinal image from memorized scene



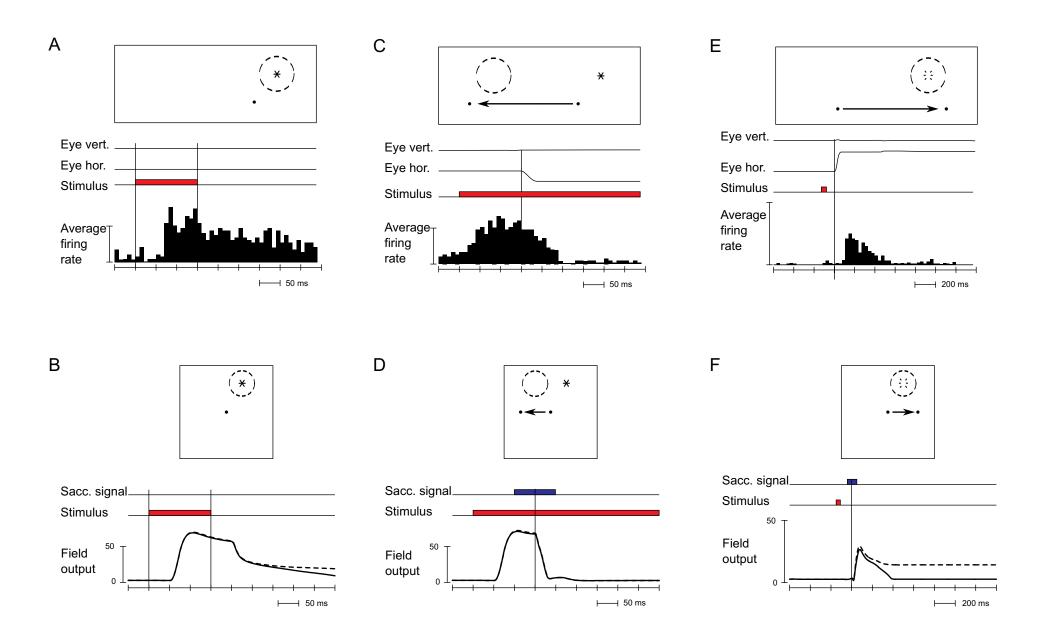
Spatial remapping during saccades



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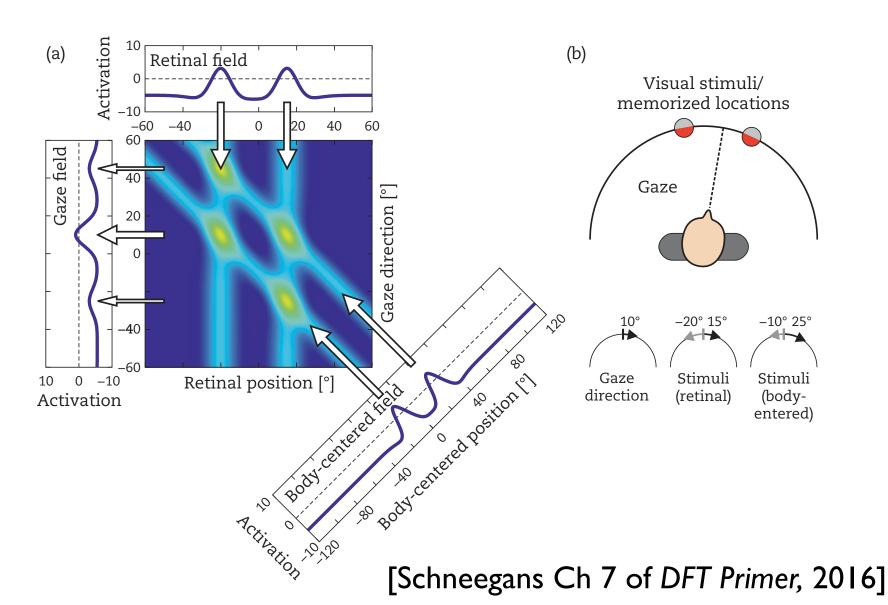
[Schneegans, Schöner Biological Cybernetics 2012]



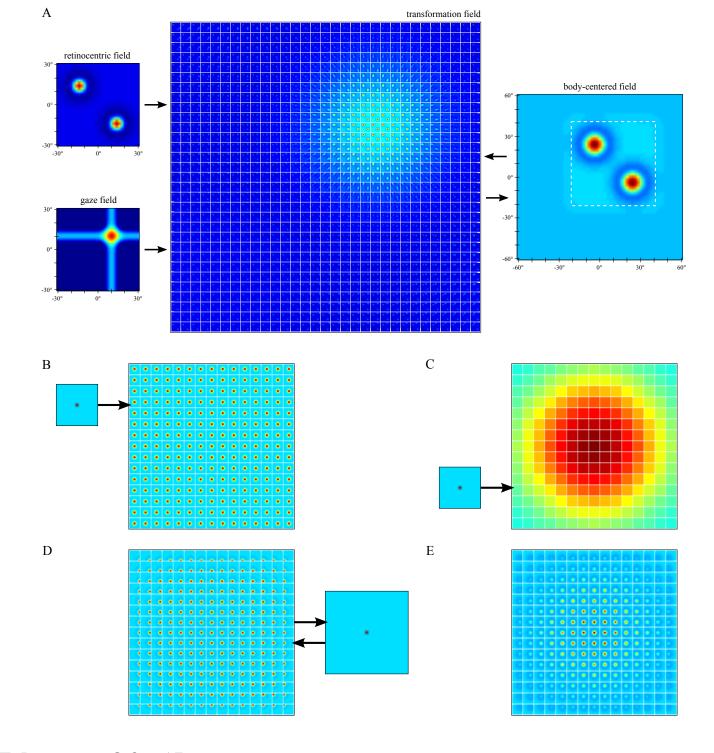
=> accounts for predictive updating of retinal representation

[Schneegans, Schöner Biological Cybernetics 2012]

estimate gaze by matching scene to memorizes scene



#### Scaling



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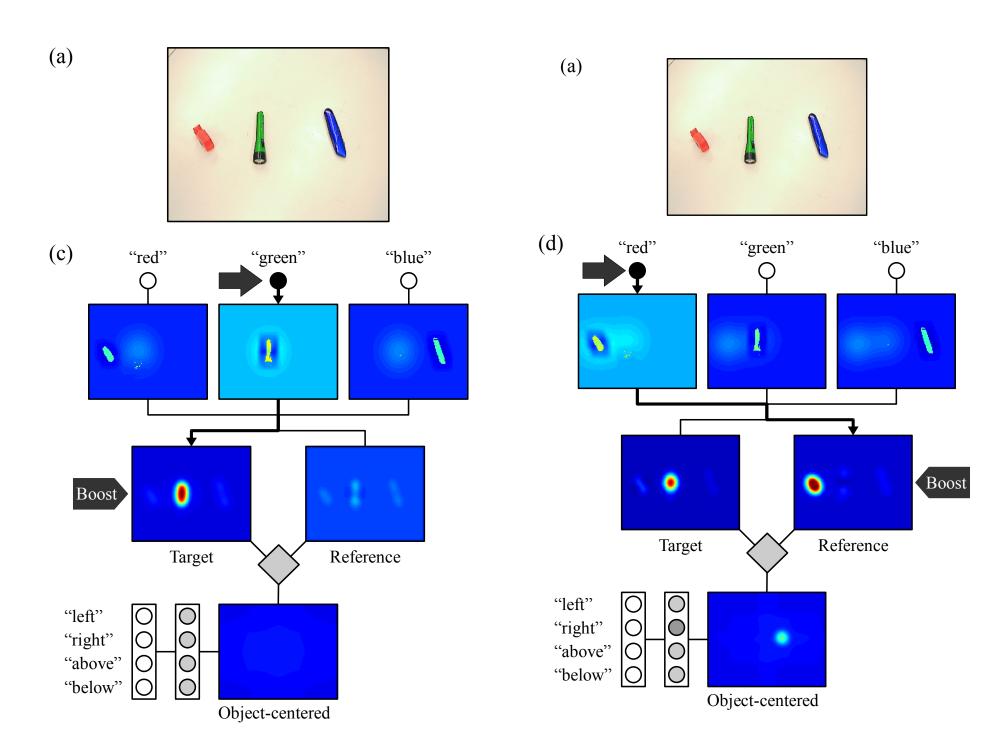
- joint representation of steering and transformed space ~ 4 dimensions
- binding through space... enables transforming only space!
- => coordinate transforms are linked to the sequentiality bottleneck!

#### **DFT** architectures

- why are the peaks and their instabilities preserved as we couple fields into architectures?
- stability => structural stability=robustness
- = invariance under change of the dynamics

#### **DFT** architectures

- controlling the instabilities of fields in an architecture is a source of flexibility
- example: architecture for perceptual grounding of spatial relations
- (=> tutorial by Mathis Richter)



[Lipinski et al: JEP:LMC (2011)]

#### **DFT** architectures

- enabling a field go through the detection instability or not homogeneous input (boost)
- reweighs the effective coupling in an architecture
- ~gating

#### Summary

- higher-dimensional dynamic fields enable new cognitive functions: binding, attentional selection, matching, visual search, coordinate transforms
- stability => robustness and enables DFT architectures in which components retain their functional states