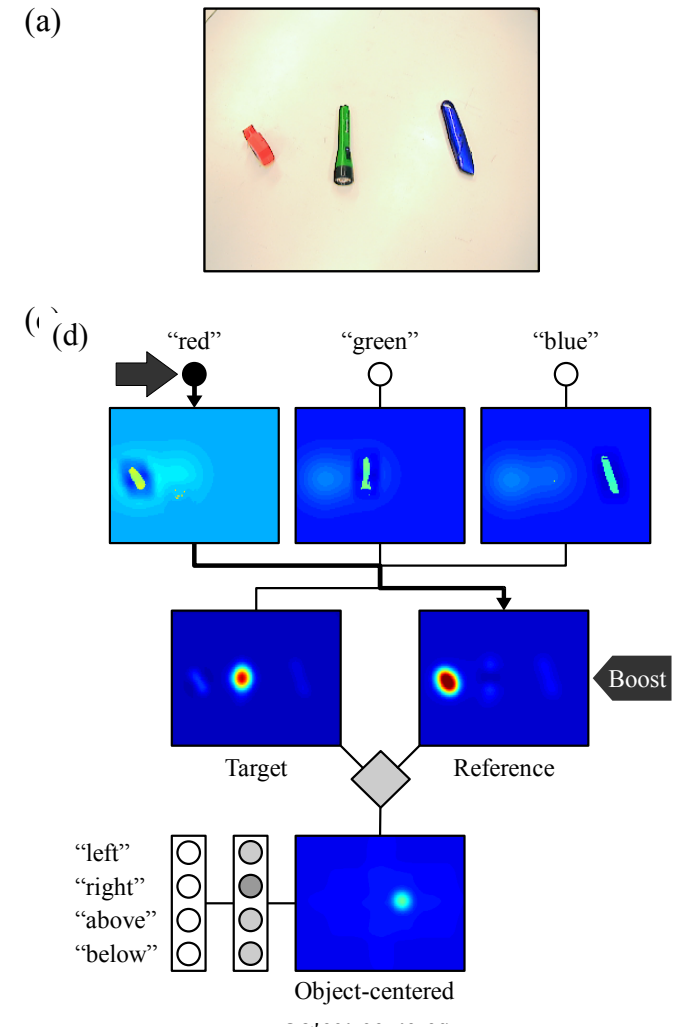
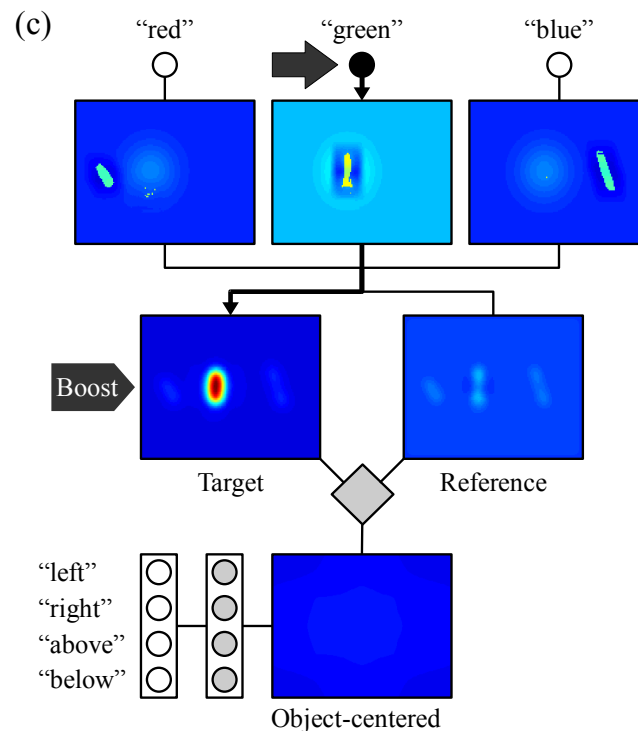
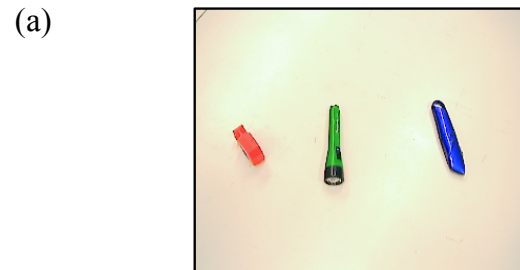


Sequential processing in DFT

Gregor Schöner

Sequence generation

■ how would sequences of processing steps arise autonomously from within the DFT architecture?



Sequence generation

- in real life all actions consist of sequences of movements, perceptual and mental acts
 - often fixed by the logic of action
 - often highly automated: routines
- but also flexible:
 - serial order: arbitrary sequences

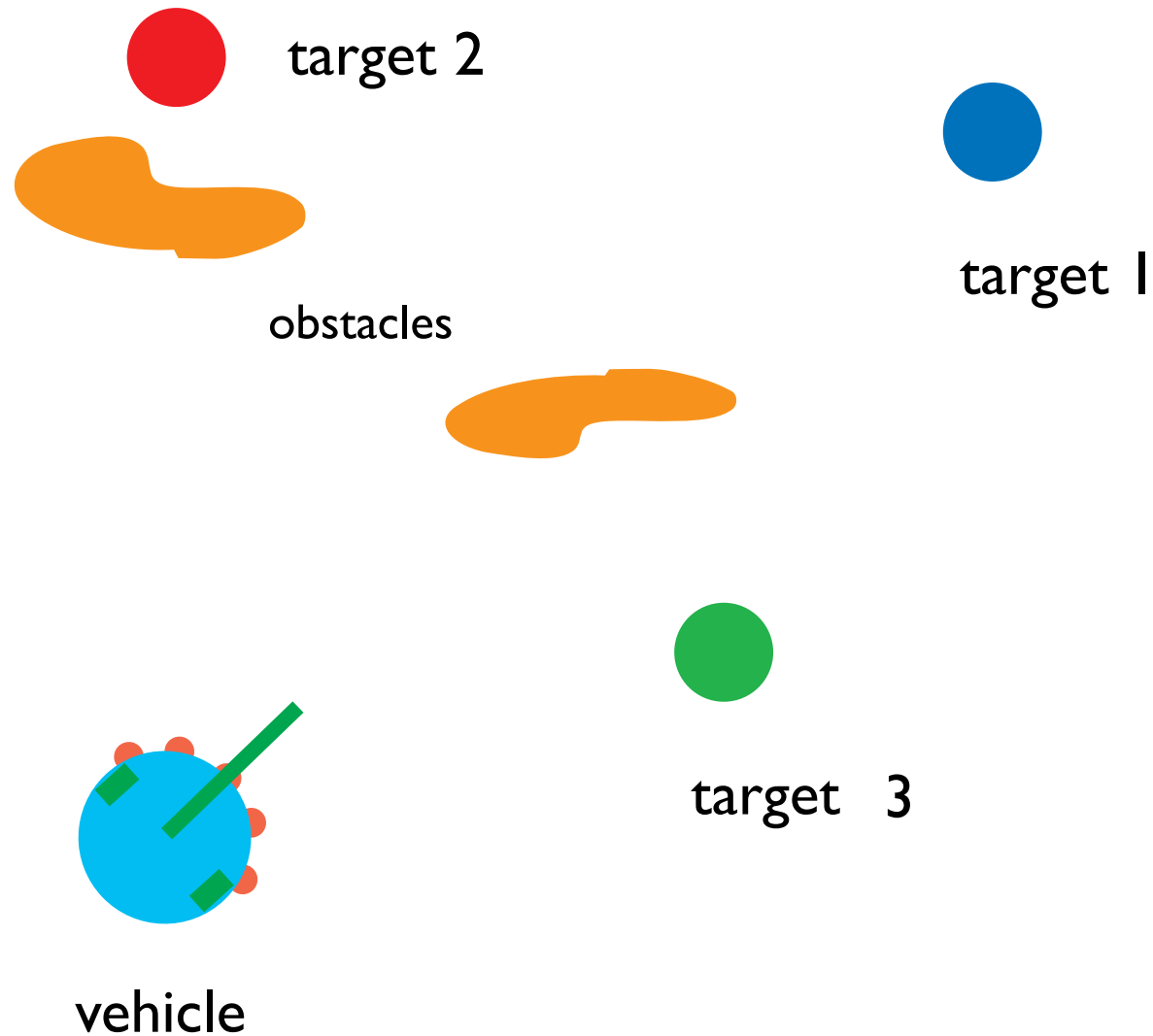
Challenge for sequence generation in DFT

- behaviors/representations are stable states
- in a sequence there is a need to switch out of one behavior to the next. How to overcome stability?
- answer: induce an instability

Illustration

■ search for objects of a given color in given serial order

1. blue
2. red
3. green



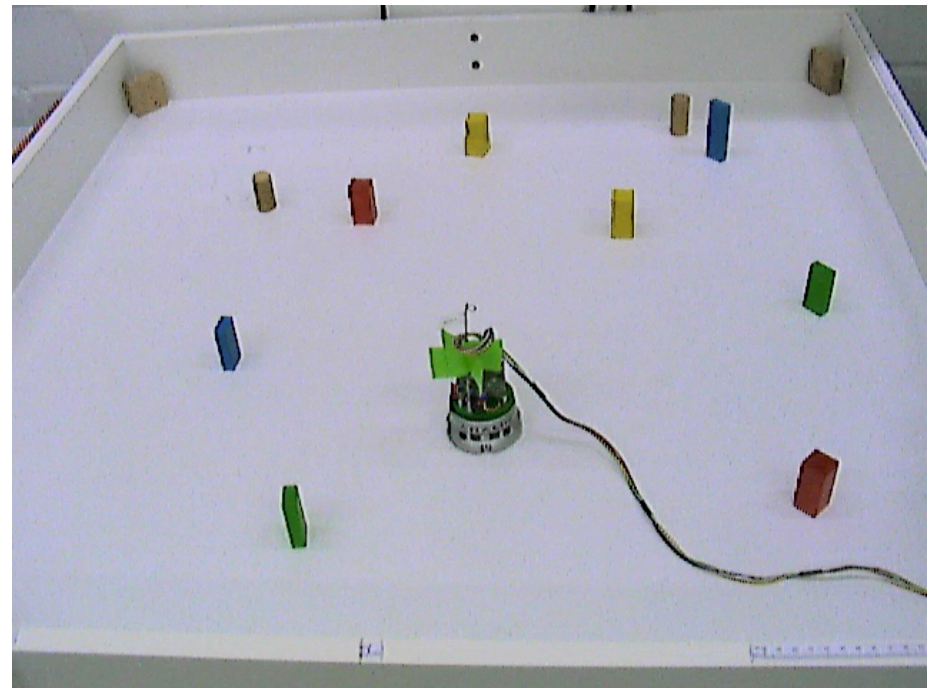
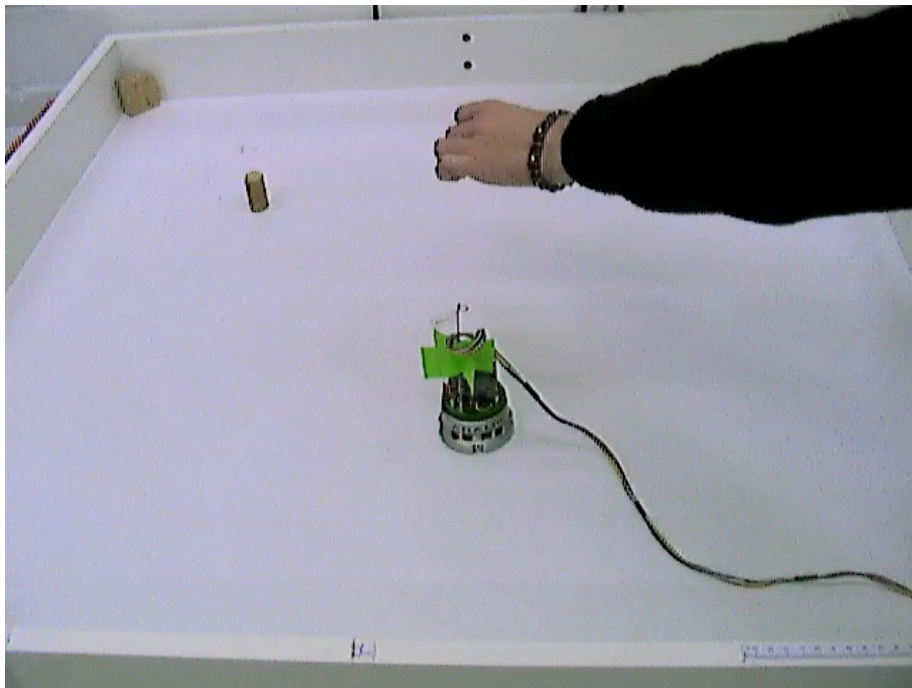
Implementation as an imitation task

- learn a serially ordered sequence from a single demonstration

- perform a serially ordered sequence with new timing

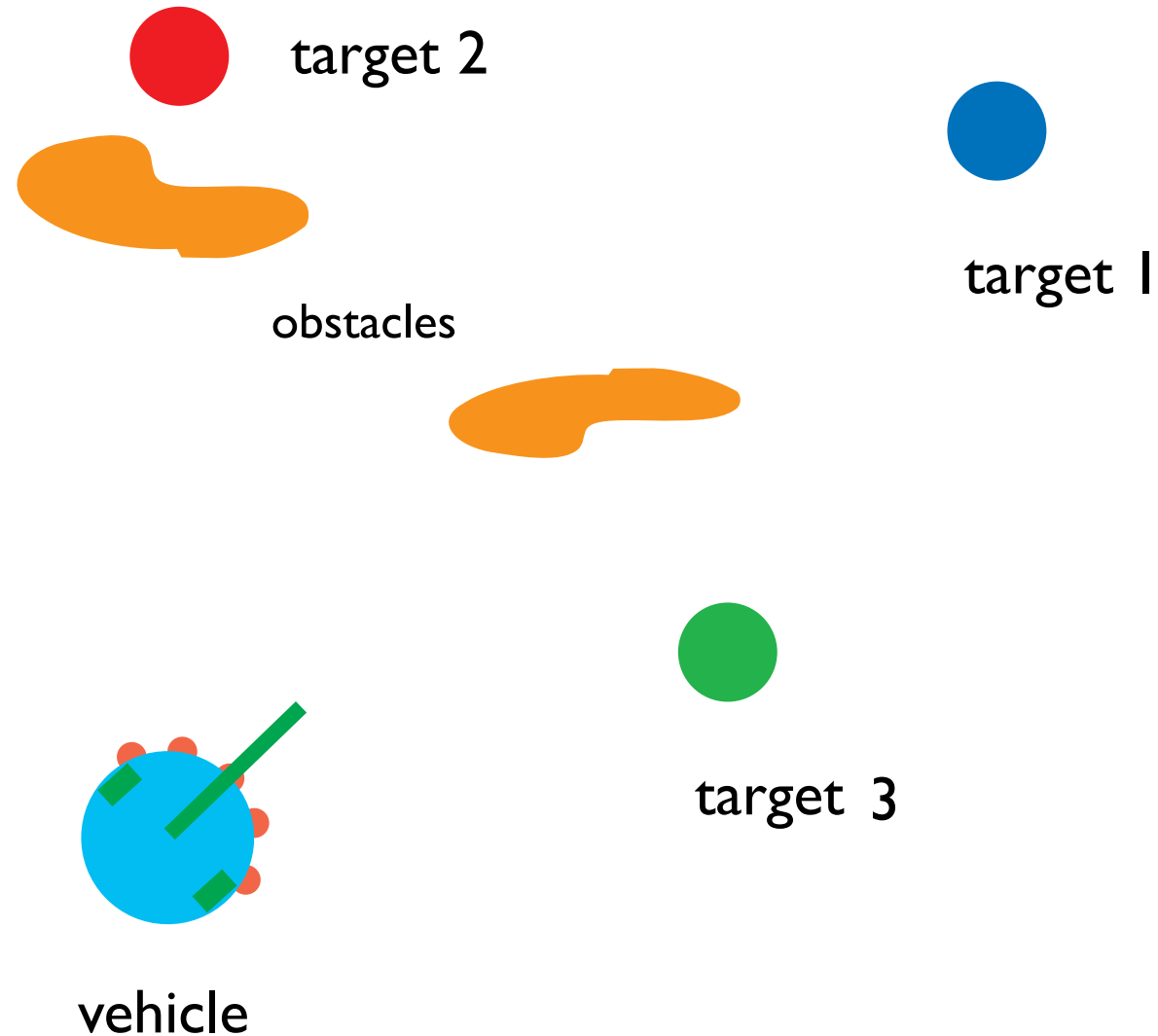
yellow-red-green-blue-red

yellow-red-green-blue-red

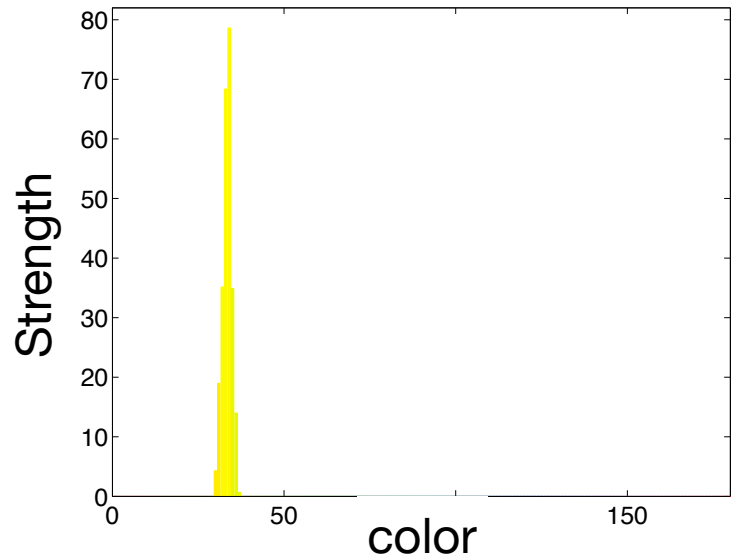


The problem of sequential processing

- each step entails a visual search for a target color



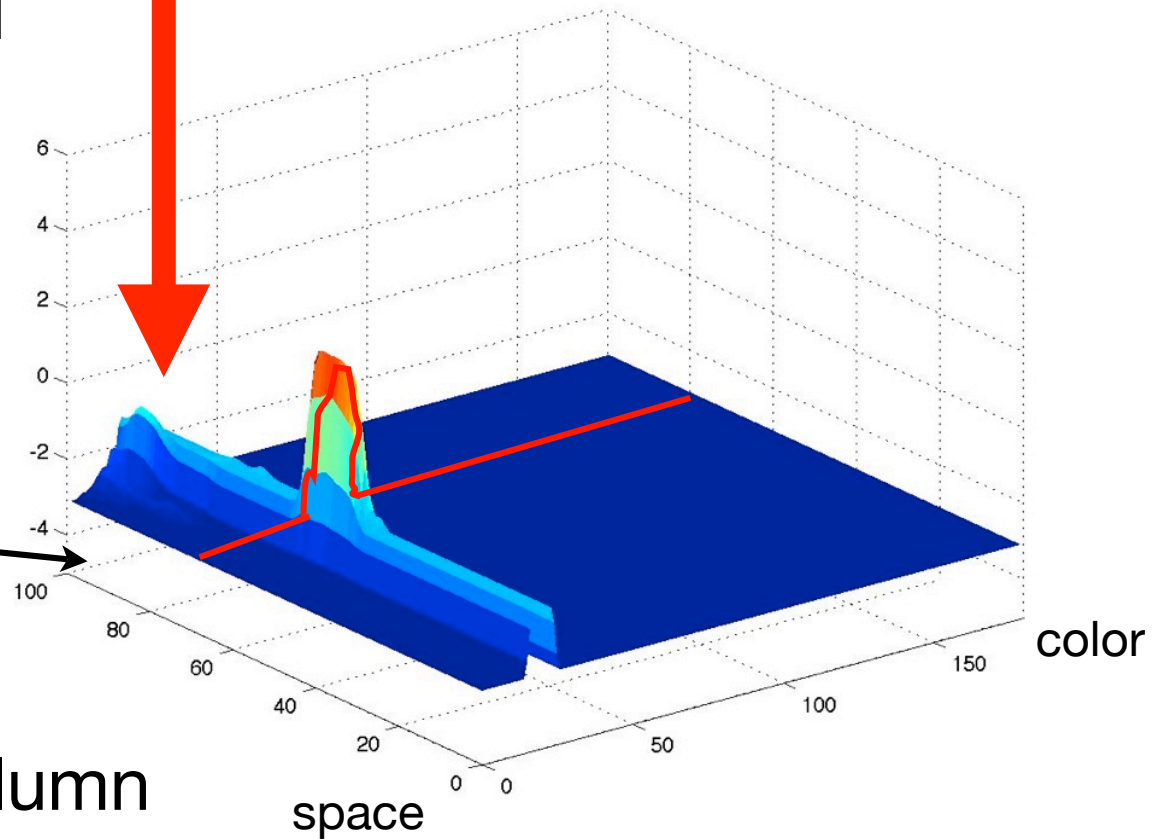
Camera image



Color histogram of the column

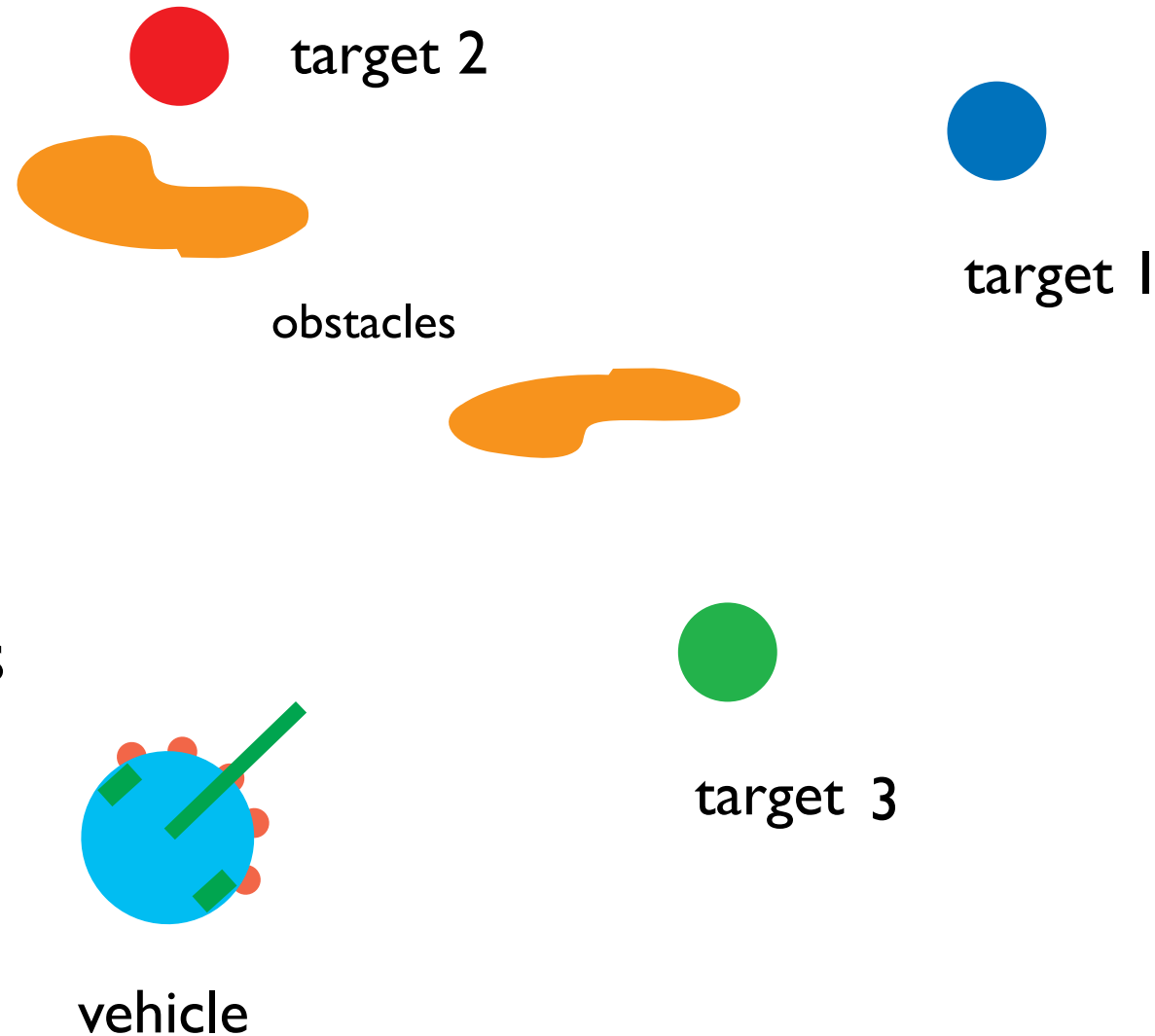
current target color

Color-space DF

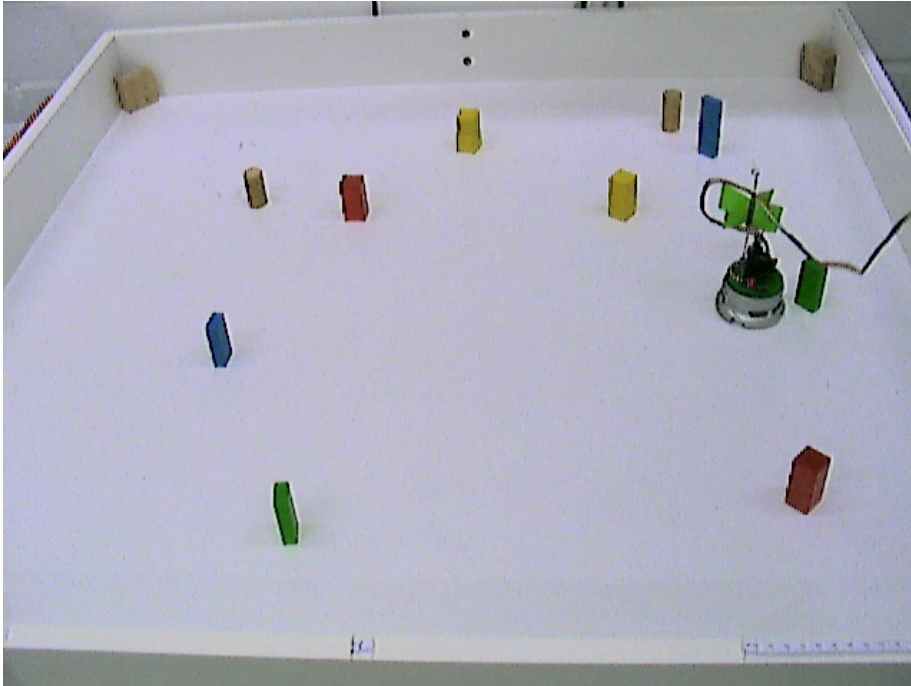


The problem of sequential processing

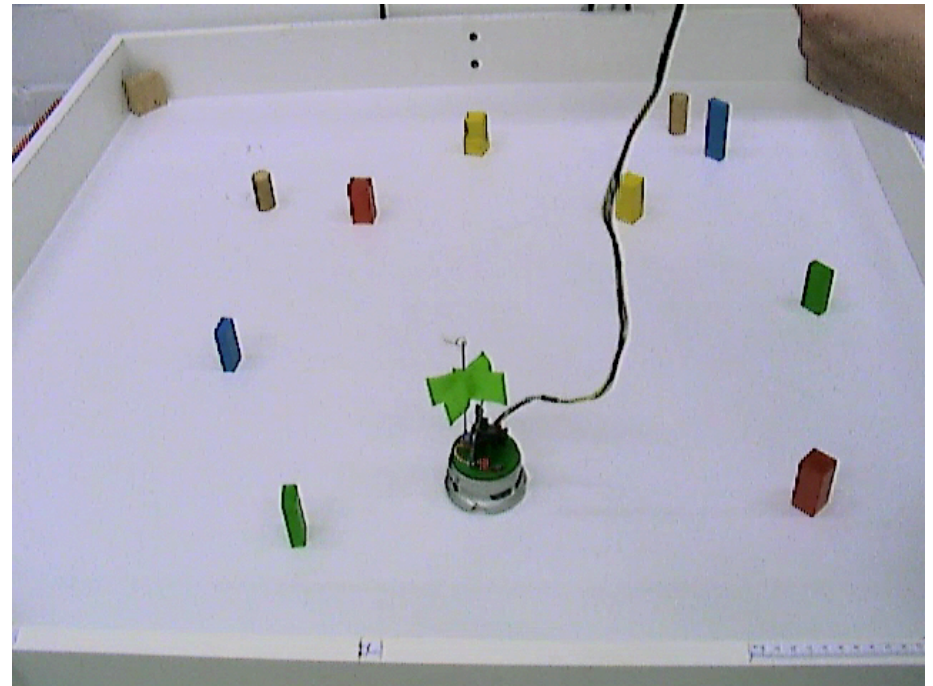
- the visual search takes a variable amount of time
- need to represent the target color by a stable peak that resists distractors

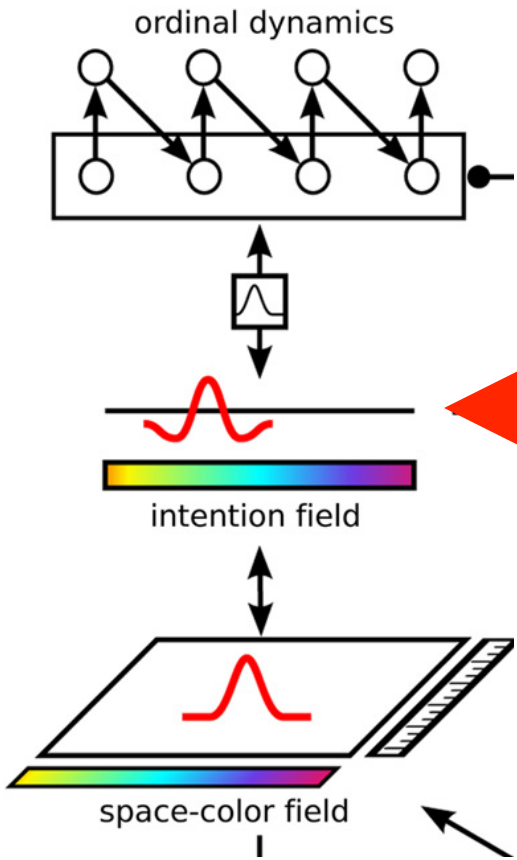


red a distractor



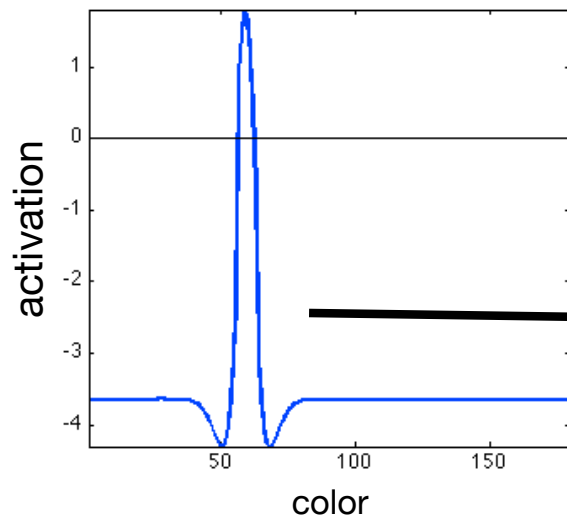
red a target



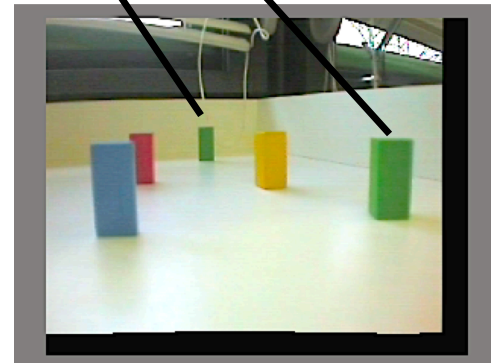
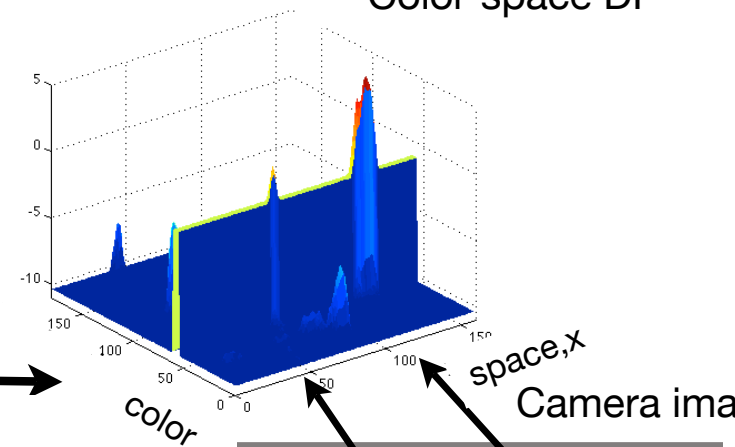


current target color

Intention DF



Color-space DF

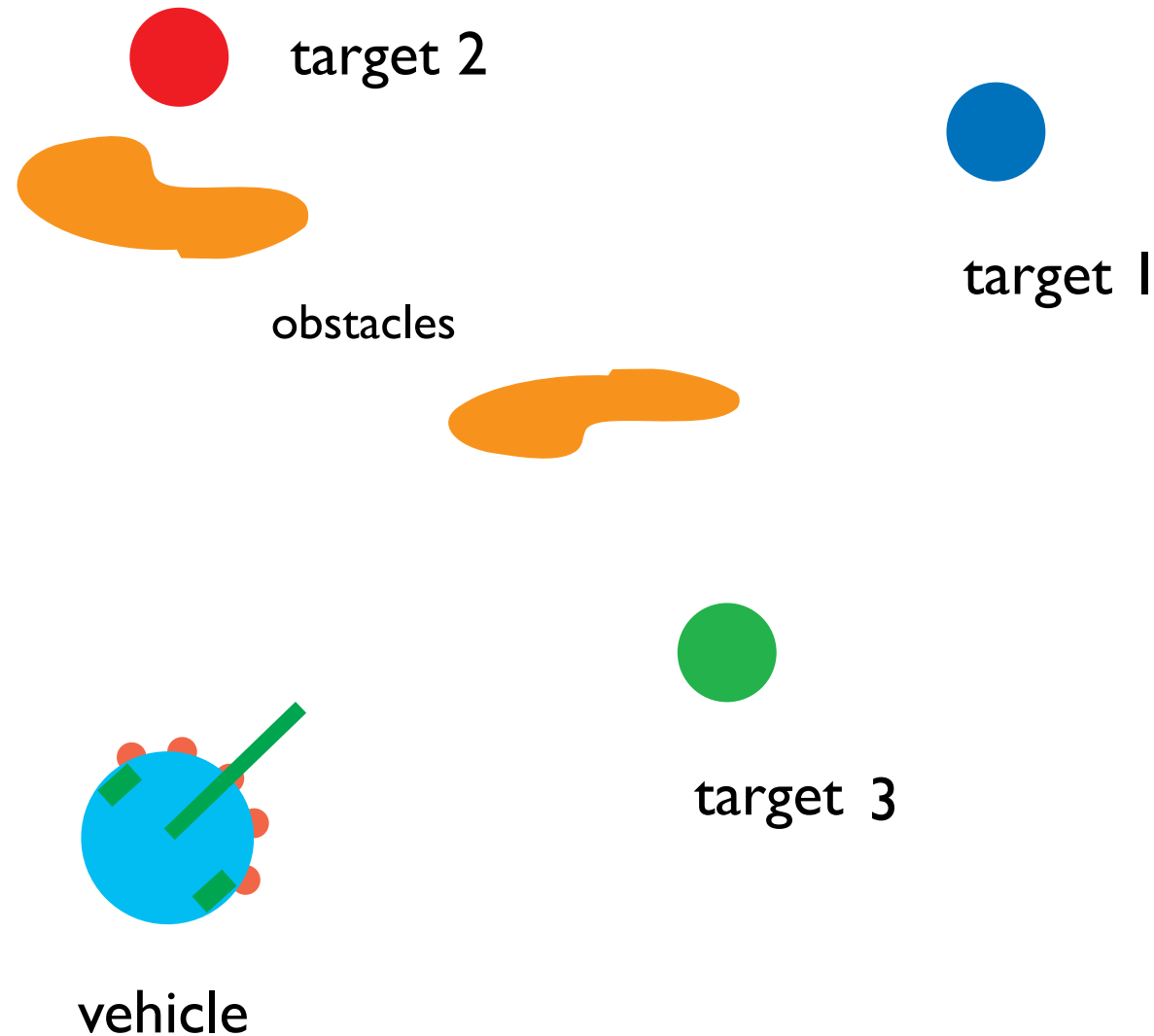


CoS DF

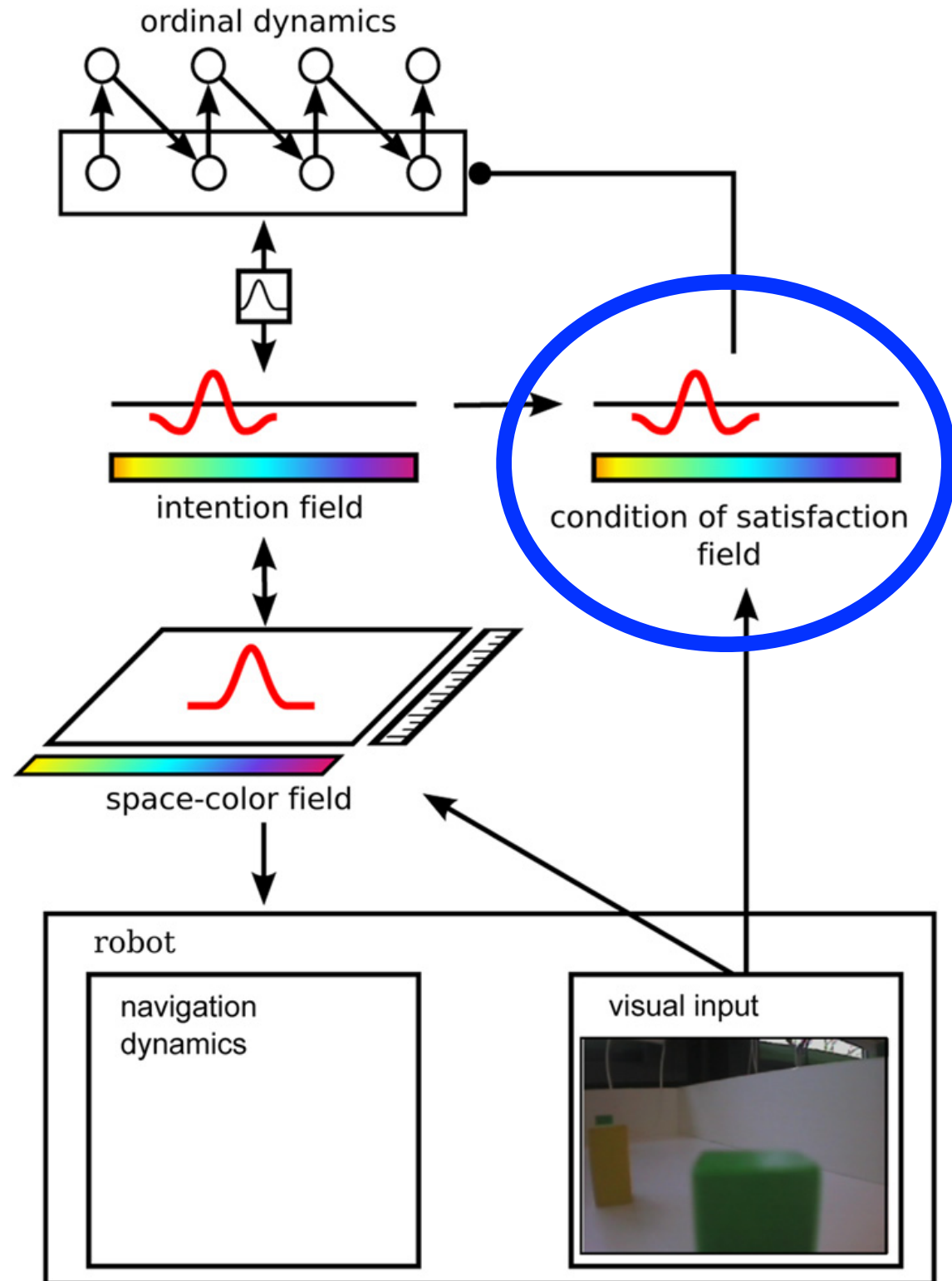


Neural dynamics of sequential processing

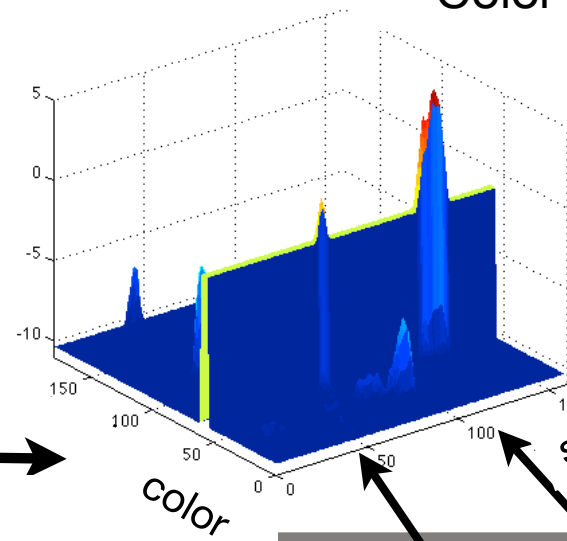
- when the target color is found, suppress the target color => instability
- switch to the next target color



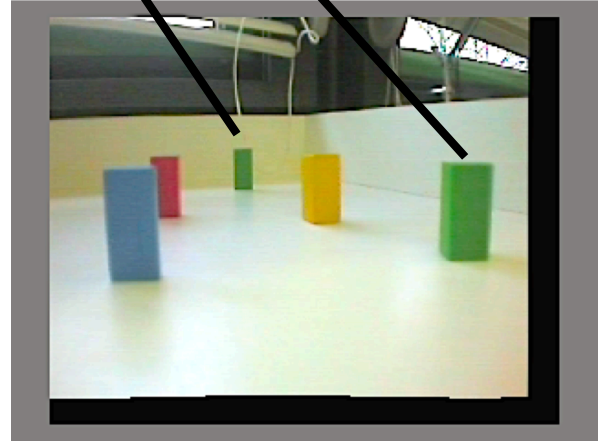
“Condition of Satisfaction” (CoS)



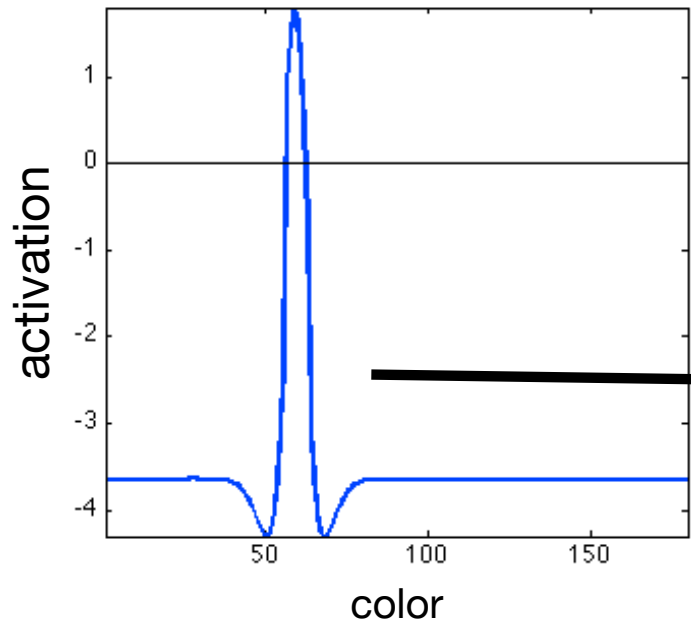
Color-space DF



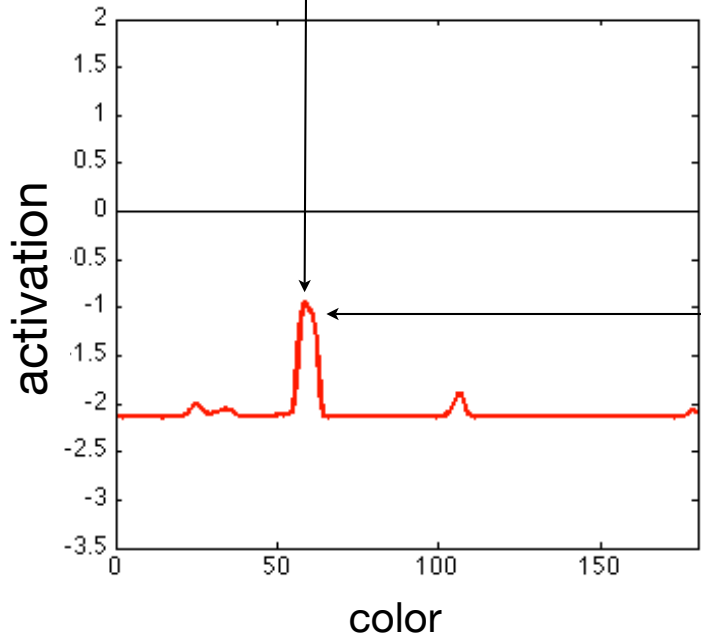
space,x
Camera image



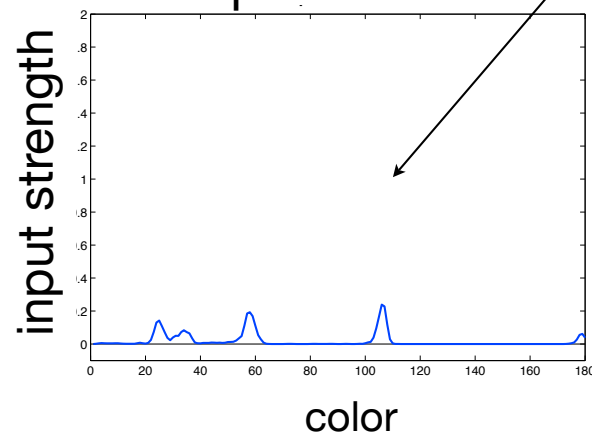
Intention DF



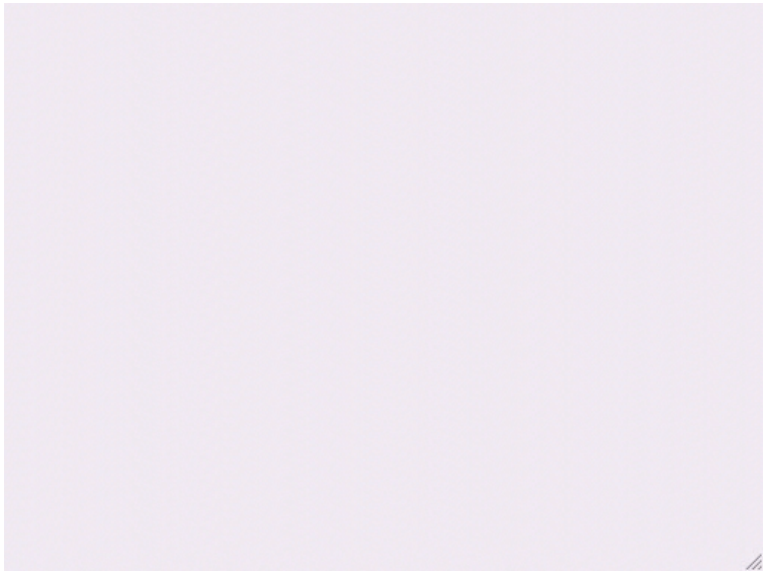
CoS DF



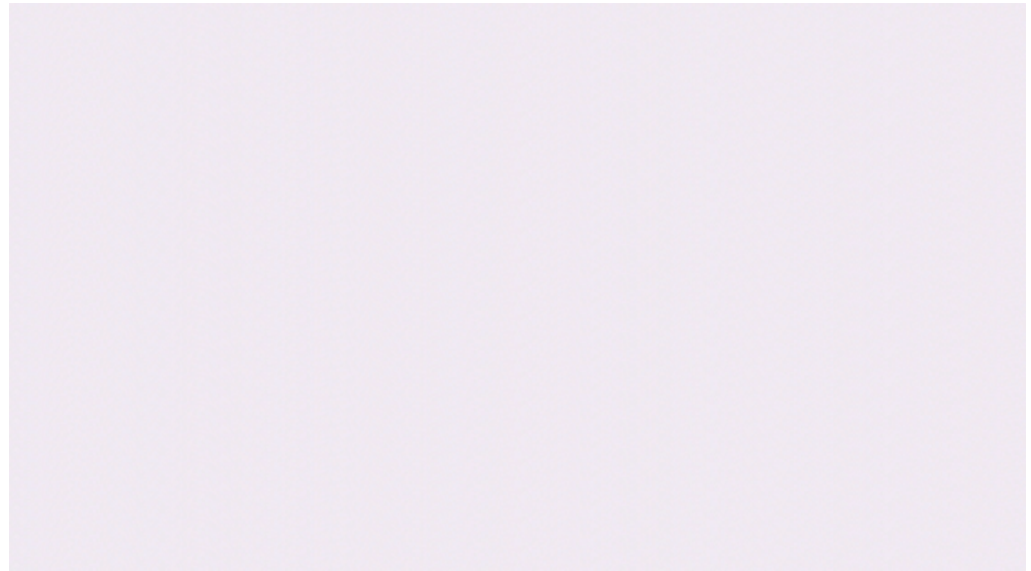
Perception for CoS



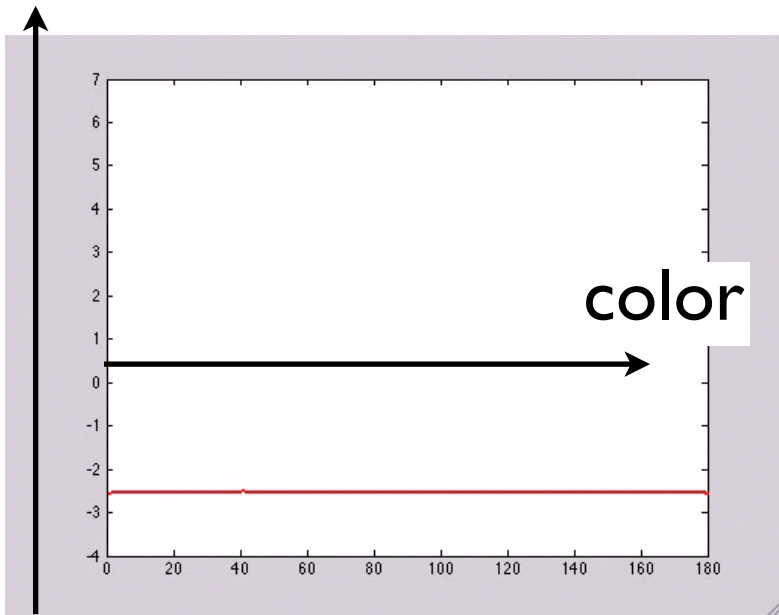
ordinal stack



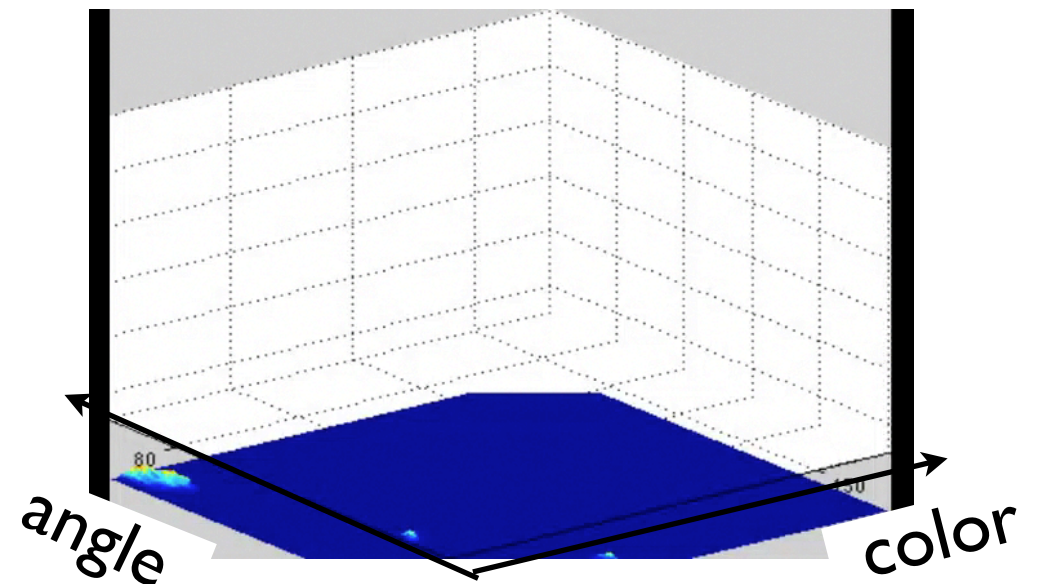
condition of satisfaction (CoS)

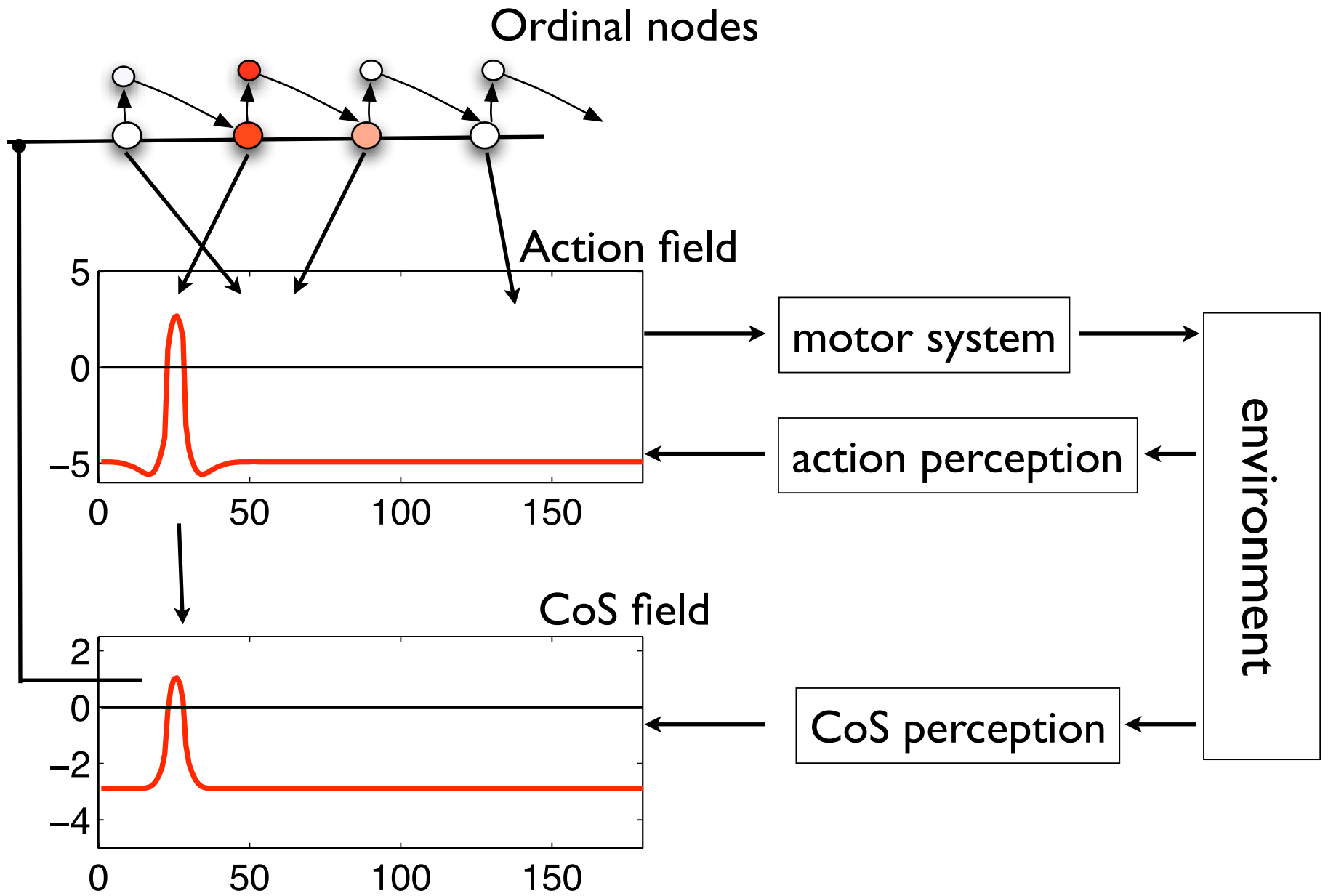


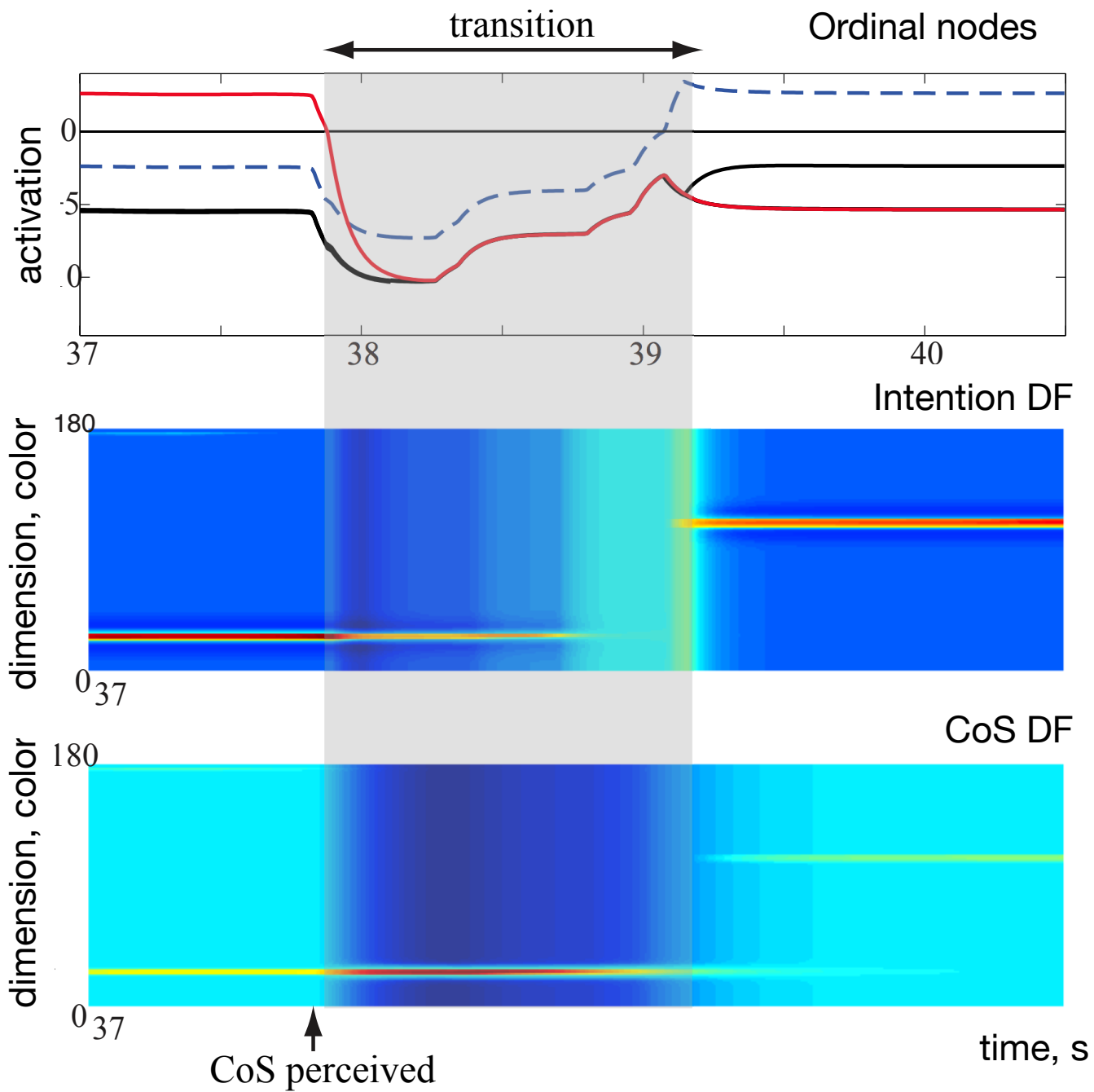
intentional state

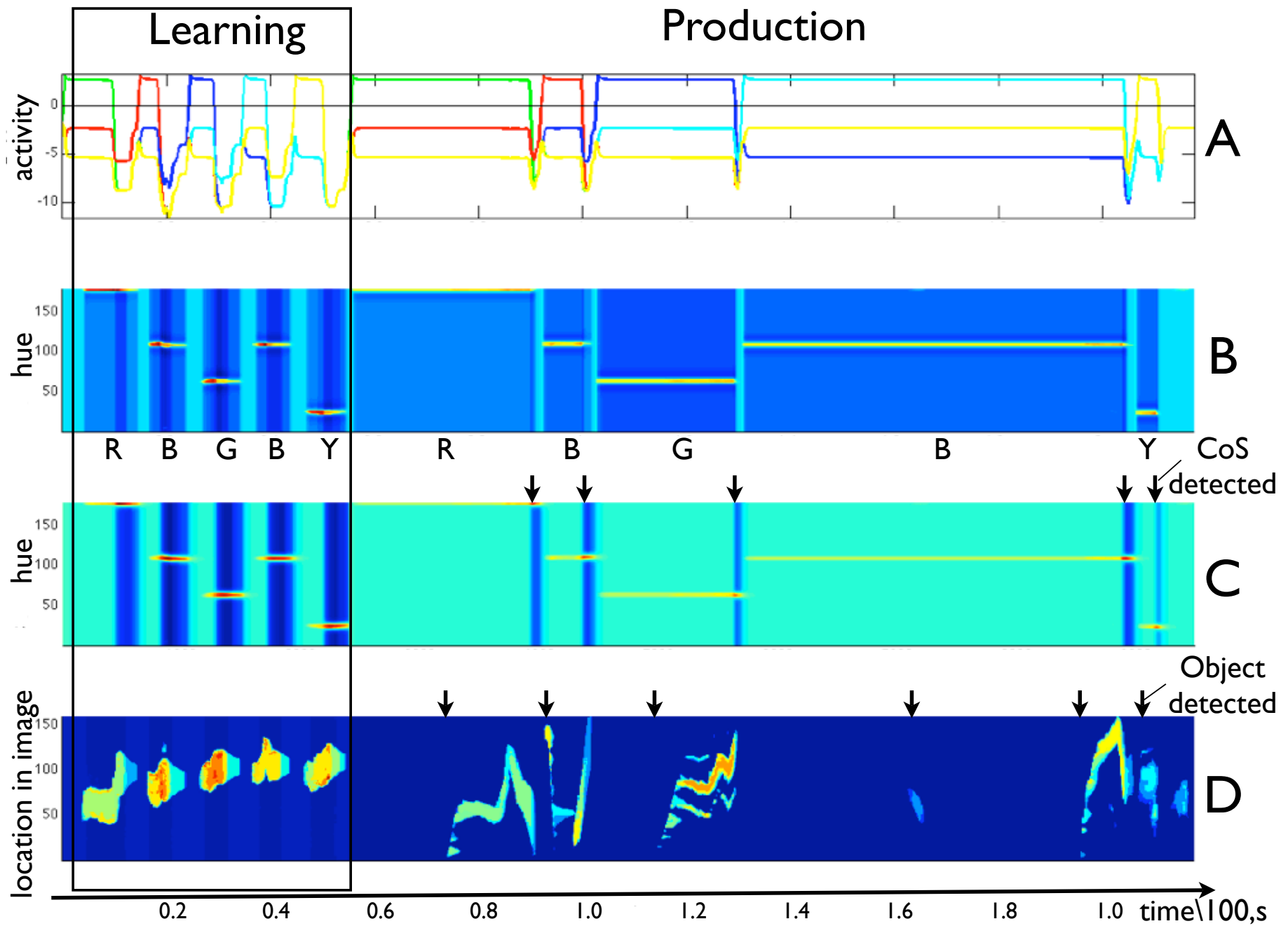


2D feature-space field



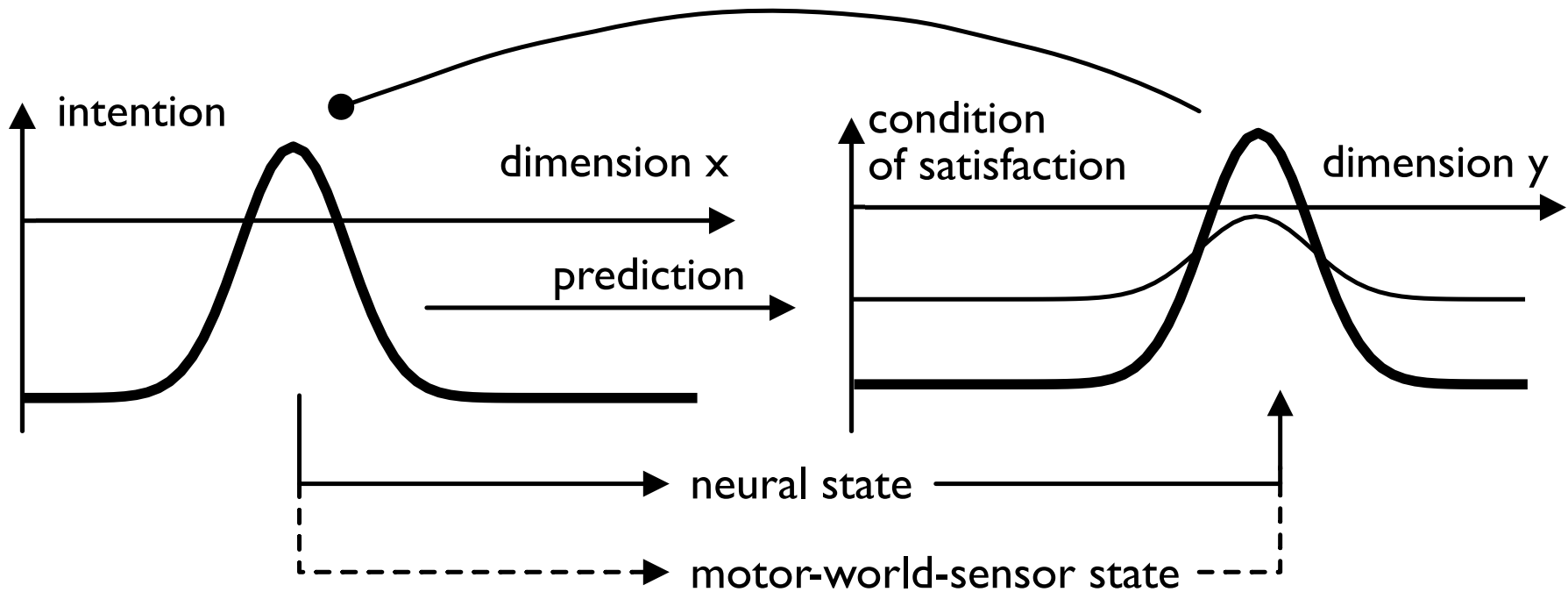






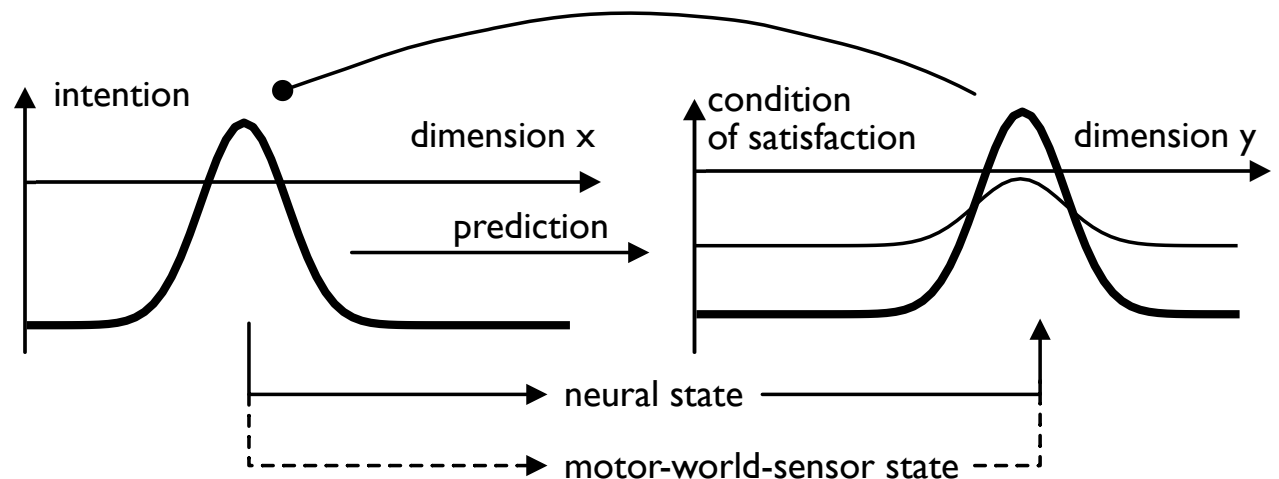
[Sandamirskaya, Schöner: *Neural Networks* 23:1163 (2010)]

Generalization

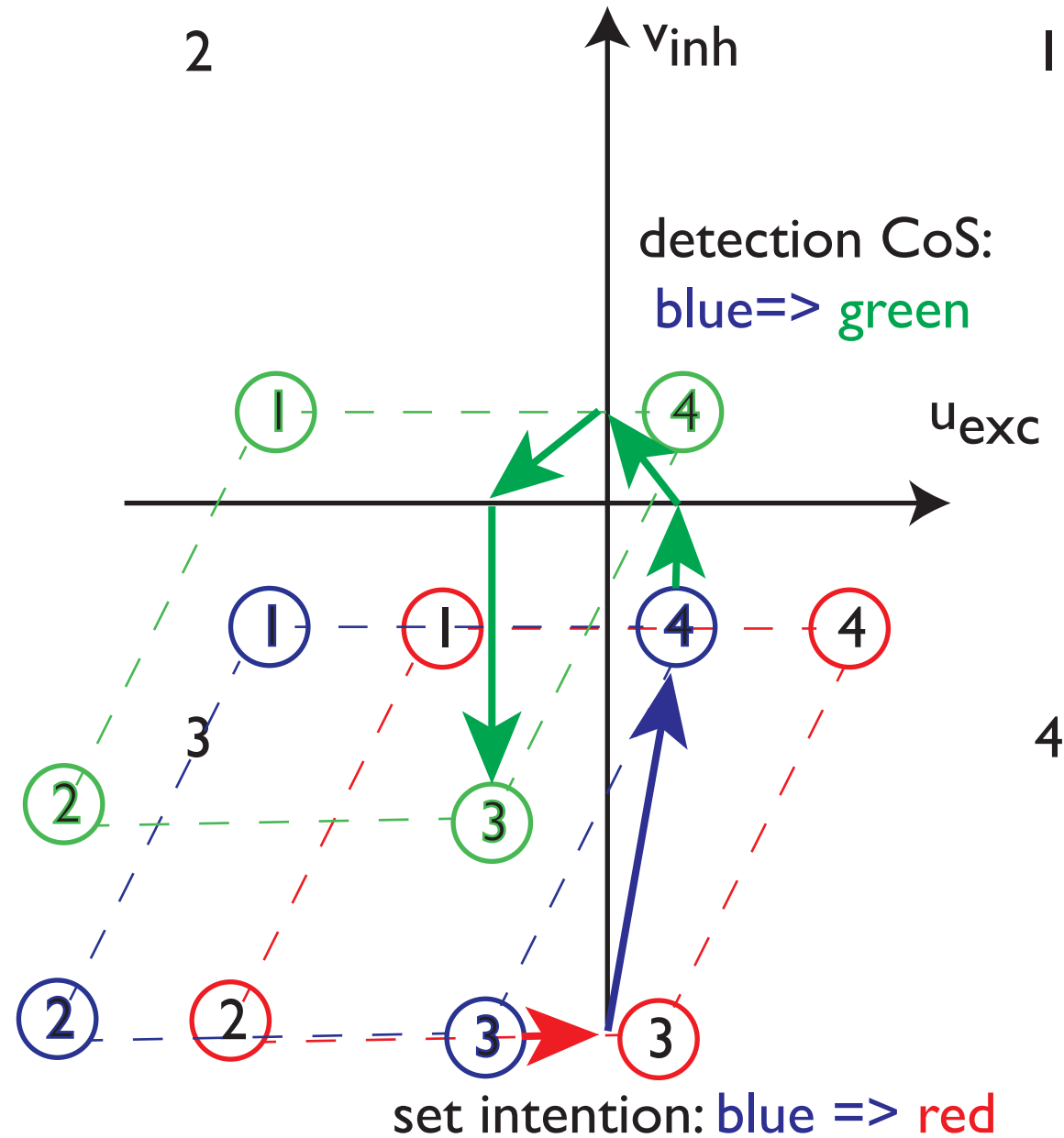


Condition of satisfaction

- detection instability in CoS as prediction and input match
- reverse detection in intention field
- reverse detection in CoS field
- => active transient

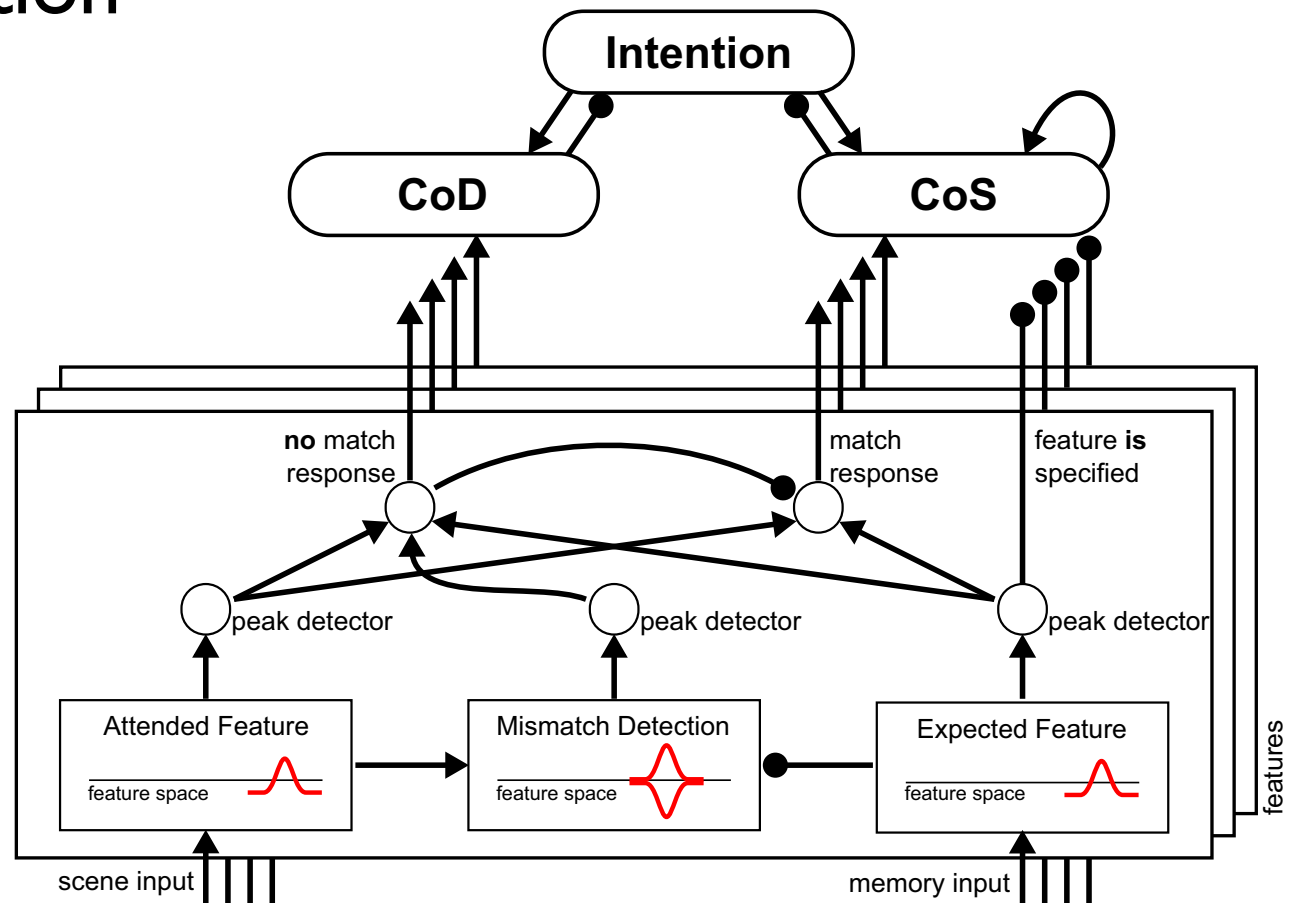


Active transient of the CoS



Match/mismatch detection

- the CoS mechanism is an instance of a more general class of neural dynamic mechanisms for match and mis-match detection

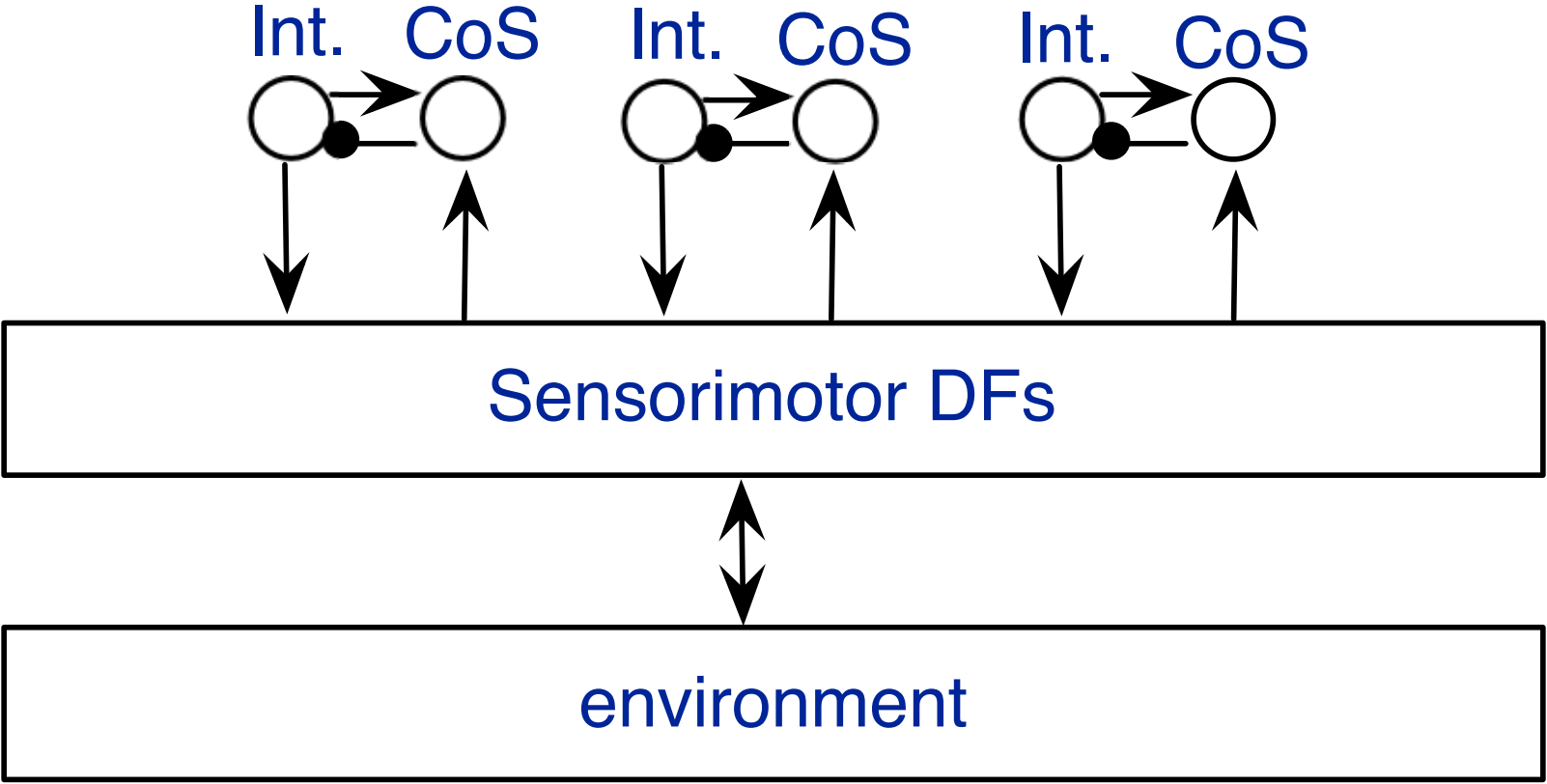


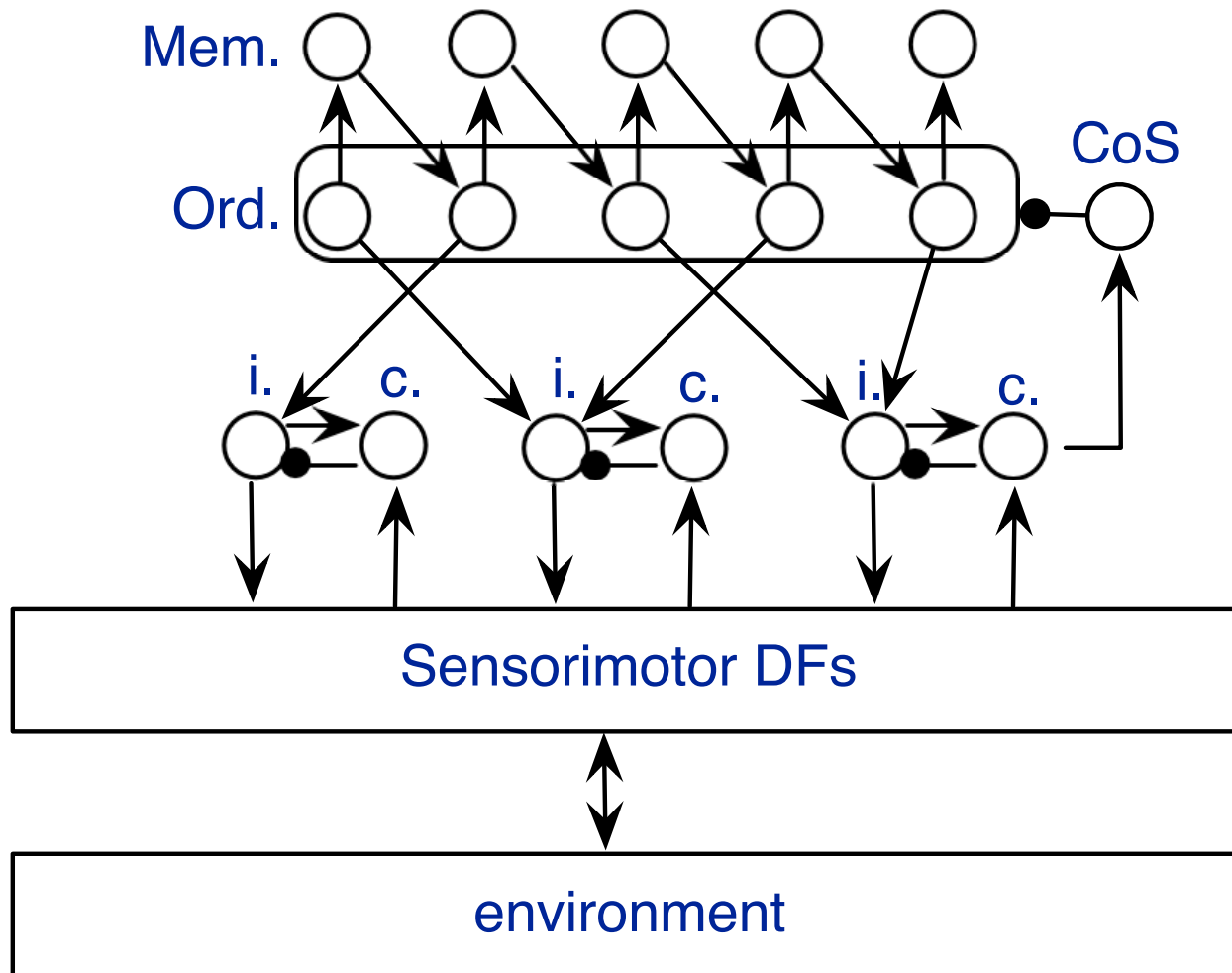
- (which develop older ideas by Grossberg and colleagues)

[Grieben et al, *PP&A* 2020]

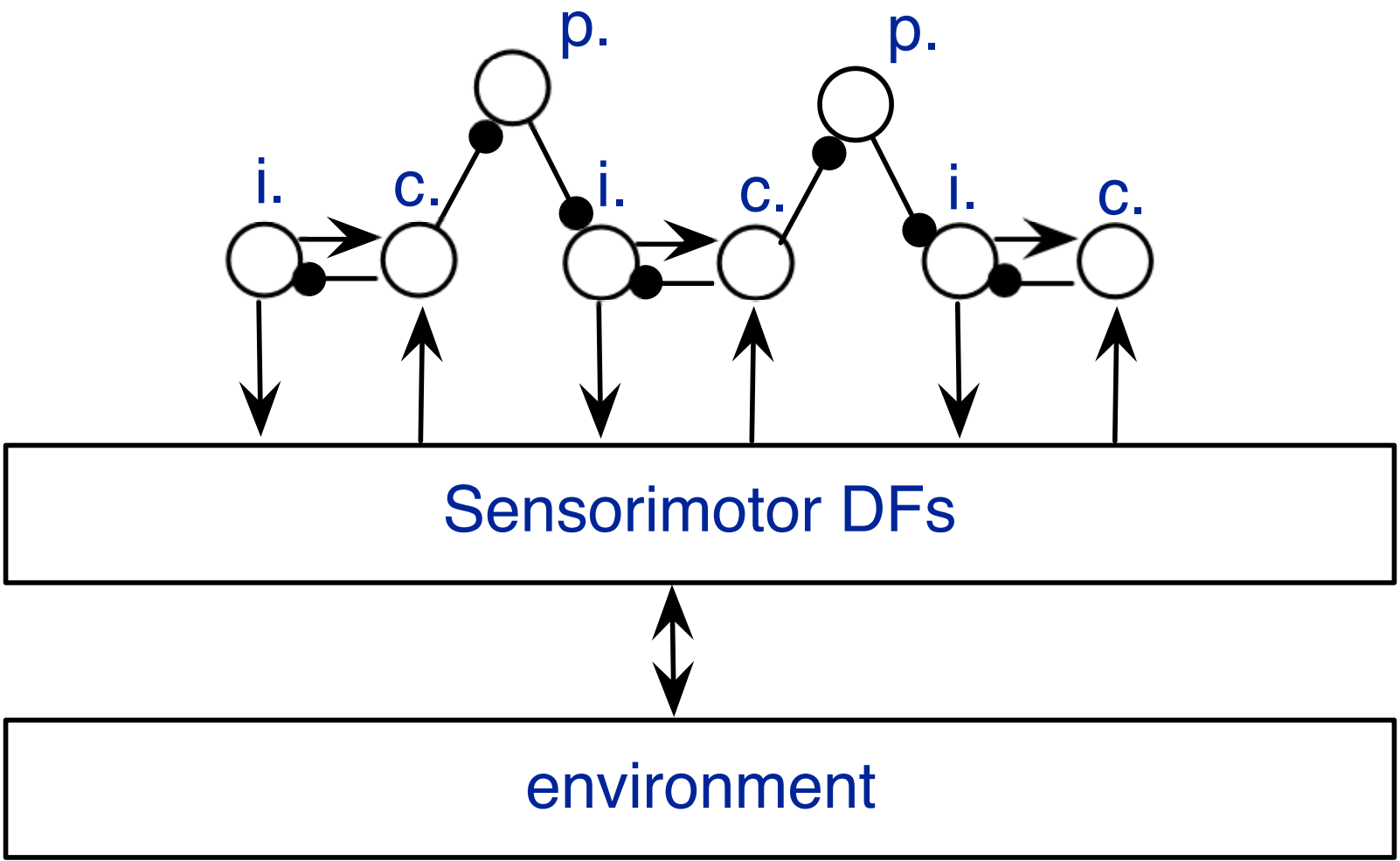
Match/mismatch detection

- see e.g. Chapter 6 by Johnson/Simmering of the DFT primer)
- => talks by Mathis Richter and Raul Grieben

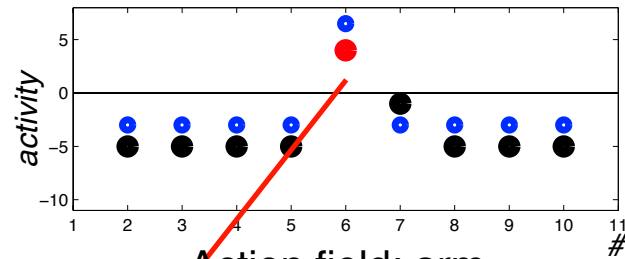




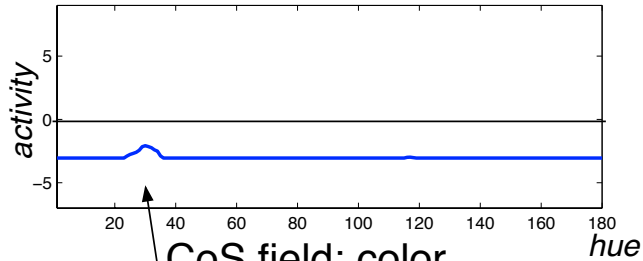
chaining



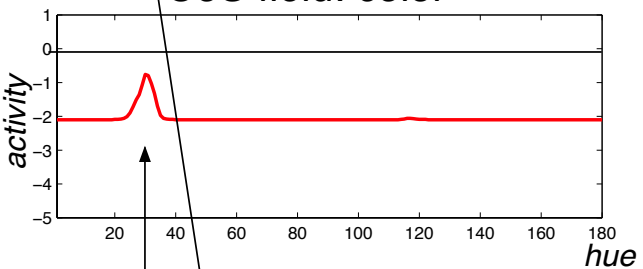
Ordinal nodes



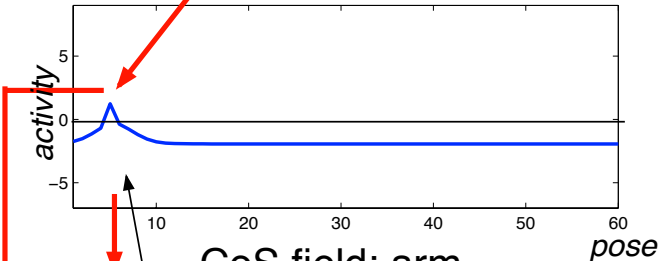
Action field: color



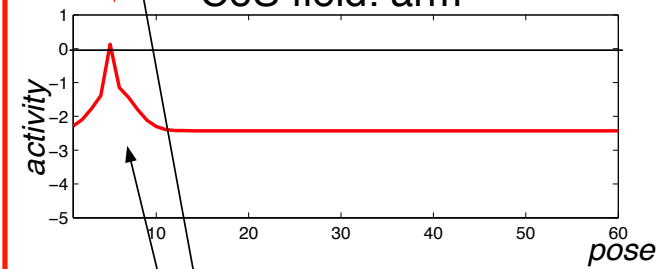
CoS field: color



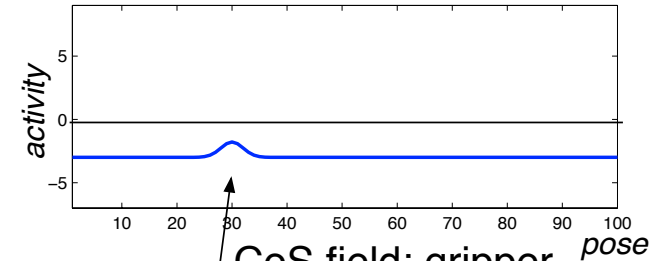
Action field: arm



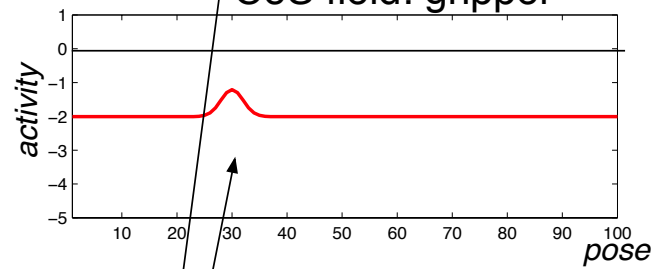
CoS field: arm



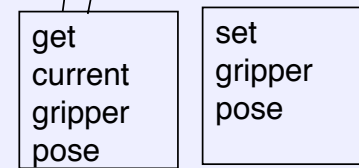
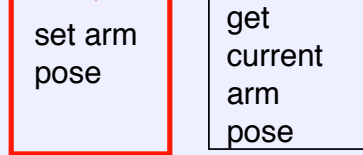
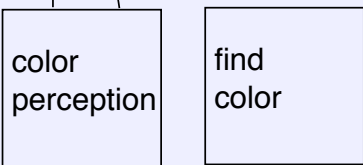
Action field: gripper



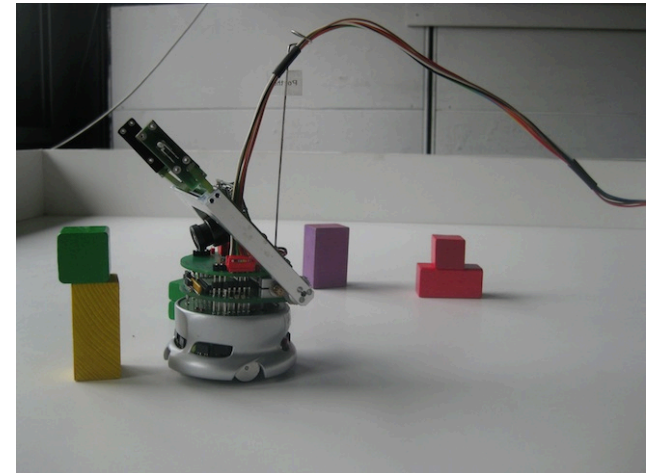
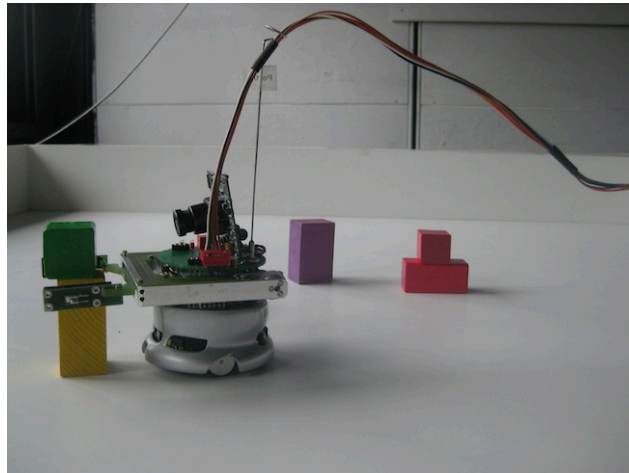
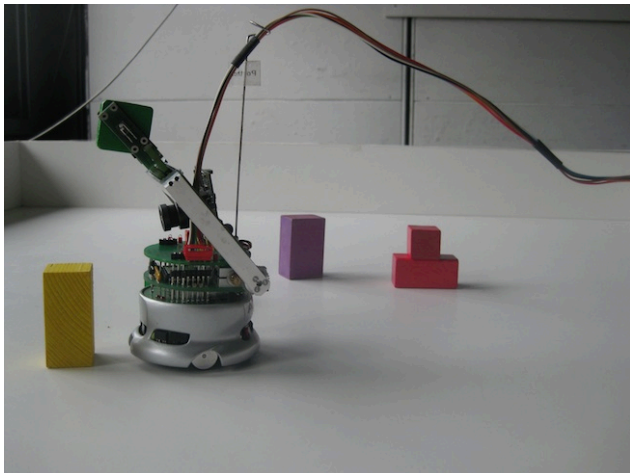
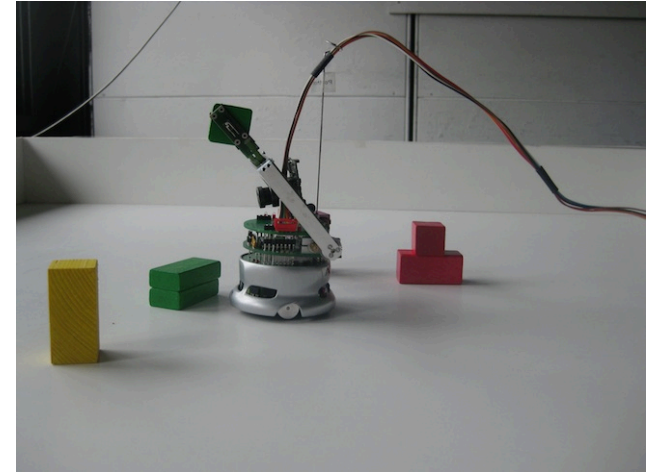
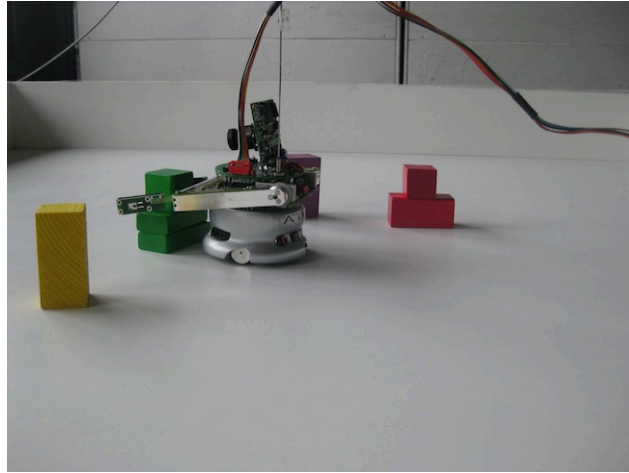
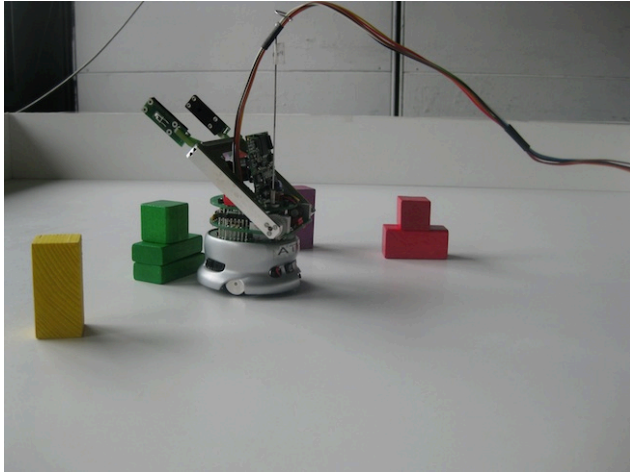
CoS field: gripper



Robot

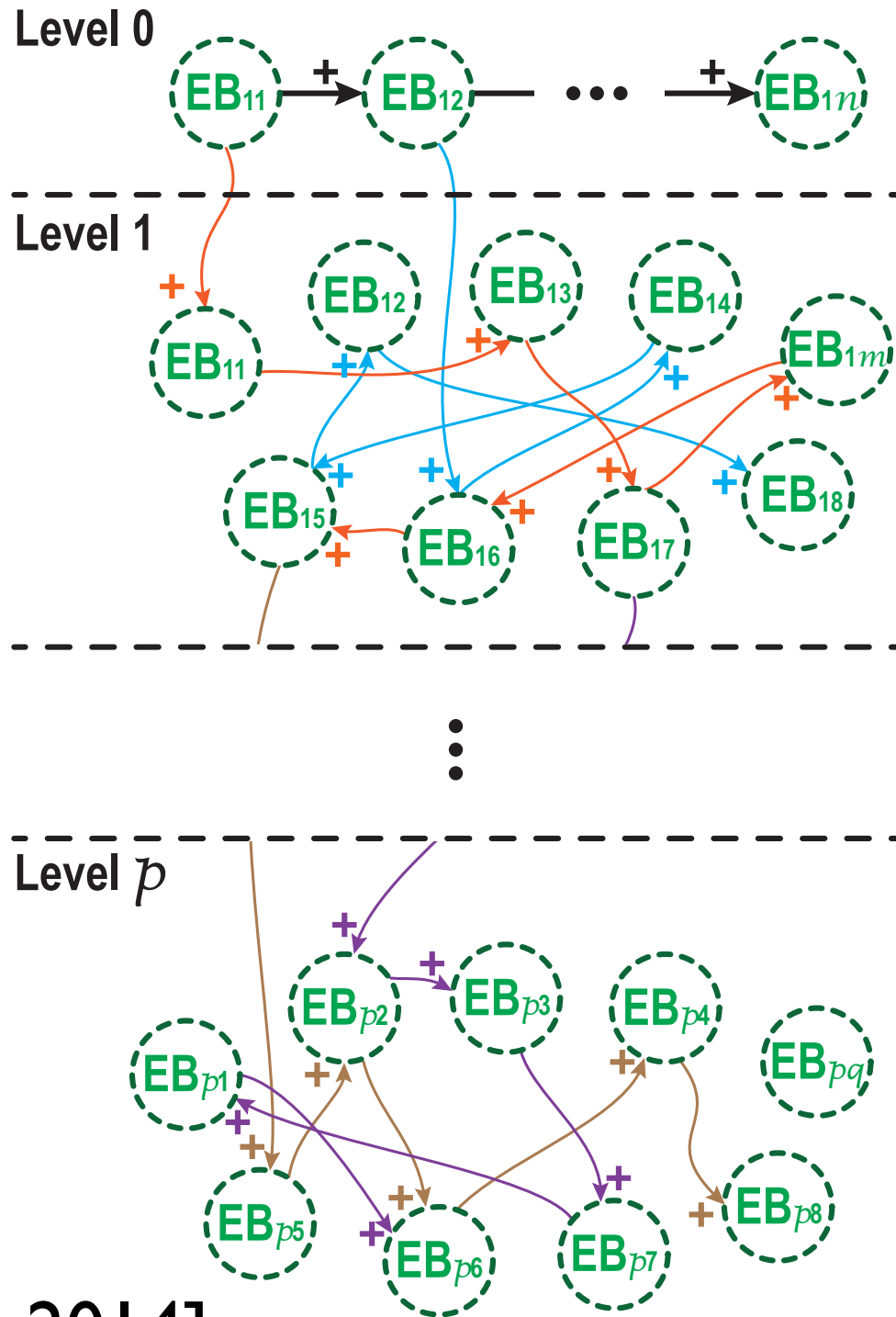


[Sandamirskaya, 2011]



[Sandamirskaya, 2011]

hierarchy



[Duran, Sandamirskaya, 2014]

Sequence generation

- sequence generation is critical to all DFT accounts for higher cognitive processes:
- => Raul Grieben on visual search
- => Mathis Richter and Daniel Sabinasz on relational concepts
- => Jan Tekülve's tutorial on sequence generation and intentionality